

Integrable and Conformal Boundary Conditions for $\hat{sl}(2)$ $A-D-E$ Lattice Models and Unitary Minimal Conformal Field Theories

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Abstract

Integrable boundary conditions are studied for critical $A-D-E$ and general graph-based lattice models of statistical mechanics. In particular, using techniques associated with the Temperley-Lieb algebra and fusion, a set of boundary Boltzmann weights which satisfies the boundary Yang-Baxter equation is obtained for each boundary condition. When appropriately specialized, these boundary weights, each of which depends on three spins, decompose into more natural two-spin edge weights. The specialized boundary conditions for the $A-D-E$ cases are naturally in one-to-one correspondence with the conformal boundary conditions of $\hat{sl}(2)$ unitary minimal conformal field theories. Supported by this and further evidence, we conclude that, in the continuum scaling limit, the integrable boundary conditions provide realizations of the complete set of conformal boundary conditions in the corresponding field theories.

1. Introduction and Overview

The notion of conformal boundary conditions in conformal field theories, in the sense introduced in [1], and the notion of integrable boundary conditions in integrable lattice models, in the sense introduced in [2], are both well developed. It is also well known that conformal field theories can be identified with the continuum scaling limit of certain critical integrable lattice models of statistical mechanics. A natural question to address, therefore, is whether similar associations can be made between the corresponding boundary conditions. We shall demonstrate here that indeed they can. In so doing, not only is the existence of deep connections between conformal and integrable boundary conditions established, but a means is also provided for gaining insights, generally not available within conformal field theory alone, into the physical nature of conformal boundary conditions.

That there should be a relationship between such integrable and conformal boundary conditions is not immediately apparent and, accordingly, the correspondence is somewhat subtle. It is known that nonintegrable boundary conditions can be identified with certain conformal boundary conditions and, conversely, we expect that integrable boundary conditions will only lead to conformal boundary conditions upon suitable specialization. Nevertheless, we shall explicitly show for all of the $\hat{sl}(2)$ cases considered here that an integrable boundary condition can, after such specialization, be naturally associated with every conformal boundary condition. Furthermore, the generality of the approach used here suggests that it is possible to obtain an integrable boundary condition corresponding to each allowable conformal boundary condition in any rational conformal field theory which is realizable as the continuum scaling limit of a Yang-Baxter-integrable lattice model.

The basic context for this work is provided by certain general results on boundary conditions. For statistical mechanical lattice models, it is well known from [3] that a model is integrable on a torus by commuting transfer matrix techniques if its Boltzmann weights satisfy the Yang-Baxter equation. A result of [2] then states that such a model is similarly integrable on a cylinder with particular boundary conditions if corresponding boundary Boltzmann weights are used which satisfy a

boundary Yang-Baxter equation. A further result, obtained in [4], is that such boundary weights can be constructed using a general procedure involving the process of fusion. For conformal field theories, there exists a fundamental consistency equation of [1] associated with the conformal boundary conditions of any rational theory on a cylinder. Furthermore, as shown in [5, 6, 7, 8, 9], the general task of solving this equation and completely classifying the conformal boundary conditions is essentially equivalent to that of classifying the representations, using matrices with nonnegative integer entries, of the fusion algebra.

In this paper, we consider the critical unitary A – D – E integrable lattice models, as introduced in [10], and the critical series of $\hat{sl}(2)$ unitary minimal conformal field theories with central charge $c < 1$, as first identified in [11, 12] and classified on a torus using an A – D – E scheme in [13, 14, 15]. As shown in [16, 17, 18], the continuum scaling limit of these lattice models is described by these field theories. Furthermore, the task of classifying the conformal boundary conditions of these theories on a cylinder was carried out in full in [9], leading to an A – D – E scheme matching that for the classification of the theories on a torus. Lattice realizations of some of these conformal boundary conditions have been identified and studied in [1, 7, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29], but in most of these cases the lattice boundary conditions are not integrable in the sense of being implemented by boundary weights which satisfy the boundary Yang-Baxter equation. Here, we use the fusion procedure of [4] to obtain systematically such integrable boundary weights and we show that, when appropriately specialized, these can be interpreted as providing realizations of the complete sets of conformal boundary conditions, as classified in [9], of the corresponding field theories on a cylinder.

In obtaining the integrable boundary conditions for the critical unitary A – D – E models, it is convenient to consider a somewhat larger class of integrable lattice models. These models, essentially introduced in [30], are restricted-solid-on-solid interaction-round-a-face models and each is based on a graph \mathcal{G} . In such a model, the spin states are the nodes of \mathcal{G} , there is an adjacency condition on the states of neighboring spins given by the edges of \mathcal{G} and the bulk Boltzmann weights are defined in terms of a particular eigenvalue and eigenvector of the adjacency matrix

of \mathcal{G} . The critical unitary A – D – E models are obtained by taking \mathcal{G} as an A , D or E Dynkin diagram and using the Perron-Frobenius eigenvalue and eigenvector of its adjacency matrix. These general graph-based models are also closely related to the Temperley-Lieb algebra, it being possible to express their bulk weights in terms of matrices of a certain representation of this algebra involving \mathcal{G} . The fact that these weights satisfy the Yang-Baxter equation is then a simple consequence of the defining relations of the algebra.

In Section 2, we consider the abstract Temperley-Lieb algebra. The results are thus independent of its representation and apply to the class of lattice models associated with the Temperley-Lieb algebra, this including the graph-based models of interest as well as certain vertex models. The main emphasis of Section 2 is on the process of fusion and its use in the construction of boundary operators which correspond to boundary weights. In particular, we list various important properties satisfied by the operators which implement fusion, including projection and push-through properties, and we obtain several results on the properties of the constructed boundary operators, including the facts that they satisfy an operator form of the boundary Yang-Baxter equation and that they can be expressed as a linear combination of fusion operators.

In Section 3, we specialize to representations of the Temperley-Lieb algebra involving graphs and study the corresponding graph-based integrable lattice models. For any such model, we then obtain an integrable boundary condition and a related set of boundary weights for each pair (r, a) , where r is a fusion level and a is a spin state or node of \mathcal{G} . In terms of the procedure of [4], the (r, a) boundary weights are constructed from a fused double block of bulk weights of width $r - 1$, with the spin states on the corners of one end of the block fixed to a . These boundary weights each depend on three spins, but we find using results from Section 2 that, upon appropriate specialization, all of the weights in a set can be simultaneously decomposed into physically more natural two-spin edge weights. We refer to the point at which this occurs as the conformal point, since it is here that we expect correspondence with conformal boundary conditions. While certain integrable boundary weights for some of the models considered here have been obtained in previous studies, specif-

ically [4, 7, 31, 32, 33, 34, 35], this crucial decomposition had not previously been observed. We conclude Section 3 by considering in detail the symmetry properties of a lattice on a cylinder with particular left and right boundary conditions.

In Section 4, we specialize to the critical unitary A – D – E models. We obtain completely explicit expressions for the boundary edge weights of the A and D cases and study A_3 , A_4 , D_4 and E_6 as important examples. We also obtain an important relation through which any A – D – E partition function can be expressed as a sum of certain A partition functions. For all of these A – D – E models, we find that, at the conformal point, the (r, a) and $(g-r-1, \bar{a})$ boundary conditions are equivalent, where g is the Coxeter number of the A – D – E Dynkin diagram \mathcal{G} and $a \mapsto \bar{a}$ is a particular involution of the nodes of \mathcal{G} . This implies that these boundary conditions are in one-to-one correspondence with the conformal boundary conditions of the unitary minimal theories $\mathcal{M}(A_{g-2}, \mathcal{G})$, as classified in [9]. We then use this and further evidence to argue that the integrable boundary conditions obtained here provide realizations of the $\mathcal{M}(A_{g-2}, \mathcal{G})$ conformal boundary conditions.

In Section 5, we briefly discuss ways in which the formalism of this paper could be applied to other models.

2. Relevant Results on the Temperley-Lieb Algebra

In this section, we list and obtain various results on the Temperley-Lieb algebra. The defining relations of this algebra were first identified in [36] and the formalism used here is largely based on that of [37, 38, 39].

Our primary objective in this section is to study operators in the abstract algebra, which, in certain representations of the algebra, correspond to bulk weights and boundary weights of a lattice model. In particular, motivated by the procedure of [4], we shall construct certain boundary operators. This procedure involves fusion, which can be regarded as a means whereby new fused operators satisfying the Yang-Baxter equation are formed by applying certain fusion operators to blocks of unfused

operators. The process of fusion was introduced in [40] and first used in the context of the Temperley-Lieb algebra in [37, 38].

2.1 The Temperley-Lieb Algebra and General Notation

The Temperley-Lieb algebra $\mathcal{T}(L, \lambda)$, with $L \in \mathbb{Z}_{\geq 0}$ and $\lambda \in \mathbb{C}$, is generated by the identity I together with operators e_1, \dots, e_L which satisfy

$$\begin{aligned} e_j^2 &= 2 \cos \lambda e_j \\ e_j e_k e_j &= e_j, \quad |j-k| = 1 \\ e_j e_k &= e_k e_j, \quad |j-k| > 1. \end{aligned} \tag{2.1}$$

The various operators to be studied in Section 2 will all be elements of $\mathcal{T}(L, \lambda)$ for some fixed L and λ .

Throughout this paper, we shall use the notation

$$s_r(u) = \begin{cases} \frac{\sin(r\lambda + u)}{\sin \lambda}, & \lambda/\pi \notin \mathbb{Z} \\ (-1)^{(r+1)\lambda/\pi} (r+u), & \lambda/\pi \in \mathbb{Z}, \end{cases} \tag{2.2}$$

for any $r \in \mathbb{Z}$ and $u \in \mathbb{C}$, with λ being the same constant as in $\mathcal{T}(L, \lambda)$.

When $\mathcal{T}(L, \lambda)$ is applied to a lattice model, λ is the crossing parameter. For the A - D - E models, this parameter is always a rational but noninteger multiple of π so that the first case of (2.2) applies. We also note that the second case of (2.2) is simply a limiting case of the first,

$$s_r(u) \Big|_{\lambda/\pi \in \mathbb{Z}} = \lim_{\lambda' \rightarrow \lambda} \frac{\sin(r\lambda' + (\lambda' - \lambda)u)}{\sin \lambda'}, \tag{2.3}$$

so that in proving identities satisfied by these functions it is often sufficient to consider only the first case.

We shall also denote, for any $r \in \mathbb{Z}$,

$$S_r = s_r(0). \tag{2.4}$$

We see, as examples, that for any λ ,

$$S_0 = 0, \quad S_1 = 1, \quad S_2 = 2 \cos \lambda. \tag{2.5}$$

2.2 Face Operators

We now introduce face operators $X_j(u)$, for $j \in \{1, \dots, L\}$ and $u \in \mathbb{C}$, as

$$X_j(u) = s_1(-u) I + s_0(u) e_j. \quad (2.6)$$

These operators correspond in a lattice model to the bulk Boltzmann weights of faces of the lattice and in this context u is the spectral parameter.

We shall represent the face operators diagrammatically as

$$X_j(u) = \begin{array}{c} \vdots \\ \vdots \\ \text{---} \diamond \text{---} \\ \vdots \\ \vdots \\ \vdots \end{array} \begin{array}{c} \\ \\ u \\ \\ \end{array} \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \quad (2.7)$$

$j-1 \quad j \quad j+1$

From the Temperley-Lieb relations (2.1) and properties of the functions (2.2), it follows that the face operators satisfy the operator form of the Yang-Baxter equation,

$$X_j(u) X_{j+1}(u+v) X_j(v) = X_{j+1}(v) X_j(u+v) X_{j+1}(u) \quad (2.8)$$

We see that the face operators also satisfy the commutation relation

$$X_j(u) X_j(v) = X_j(v) X_j(u) \quad (2.9)$$

and the operator form of the inversion relation

$$X_j(-u) X_j(u) = s_1(-u) s_1(u) I. \quad (2.10)$$

2.3 Fusion Operators

We now proceed to a consideration of some aspects of the process of fusion. In particular, we shall state some important properties of fusion operators. The proofs of these or similar properties can be found in [37, 38].

In general, fusion levels correspond to representations of a Lie algebra. In the case considered here, this algebra is $\hat{\mathfrak{sl}}(2)$ and the fusion levels are labeled by a single integer $r \in \{1, 2, \dots, g\}$, where the maximum fusion level g depends on λ according to

$$g = \begin{cases} h, & \lambda = k\pi/h, \text{ } k \text{ and } h \text{ coprime integers, } h > 1 \\ \infty, & \text{otherwise.} \end{cases} \quad (2.11)$$

We note that for the A - D - E lattice models, the first case of (2.11) always applies.

We now introduce fusion operators P_j^r , for $r \in \{1, \dots, \min(g, L+2)\}$ and $j \in \{1, \dots, L+3-r\}$, these being defined recursively by

$$\begin{aligned} P_j^1 &= P_j^2 = I \\ P_j^r &= \frac{1}{S_{r-1}} P_{j+1}^{r-1} X_j(-(r-2)\lambda) P_{j+1}^{r-1}, \quad r \geq 3. \end{aligned} \quad (2.12)$$

We note that, for finite g , the restriction of fusion levels to $r \leq g$ is necessary in order to avoid $S_{r-1} = 0$ in the denominator in (2.12).

We shall represent the fusion operators diagrammatically as

$$P_j^r = \begin{array}{c} \begin{array}{ccccccc} & & \vdots & & \vdots & & \\ & & \diagup & & \diagdown & & \\ & & \text{---} & & \text{---} & & \\ & & \diagdown & & \diagup & & \\ & & \vdots & & \vdots & & \end{array} \\ \begin{array}{ccccccc} \vdots & & \vdots & & \vdots & & \vdots \\ j-1 & & j & & j+r-3 & & j+r-2 \end{array} \end{array}. \quad (2.13)$$

In general, P_j^r can be expressed in terms of I and e_j, \dots, e_{j+r-3} , the cases of the first few fusion levels being

$$\begin{aligned} P_j^1 &= P_j^2 = I, & P_j^3 &= I - \frac{1}{S_2} e_j \\ P_j^4 &= I - \frac{S_2}{S_3} (e_j + e_{j+1}) + \frac{1}{S_3} (e_j e_{j+1} + e_{j+1} e_j). \end{aligned} \quad (2.14)$$

The fusion operators can also be expressed as

$$P_j^r = \prod_{k=2}^{r-1} (S_k)^{k-r} \cdot \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \text{Diamond shape with labels } -\lambda, -2\lambda, -\lambda, -\lambda, -2\lambda, -\lambda, -\lambda \\ \vdots \\ \vdots \\ \vdots \end{array} = \prod_{k=2}^{r-1} (S_k)^{k-r} \cdot \begin{array}{c} \vdots \\ \vdots \\ \vdots \\ \text{Diamond shape with labels } -\lambda, -2\lambda, -\lambda, -\lambda, -2\lambda, -\lambda, -\lambda \\ \vdots \\ \vdots \\ \vdots \end{array} \cdot (2.15)$$

$j-1 \quad j \quad j+r-3 \quad j+r-2$

A key property of the fusion operators is that they are projectors,

$$(P_j^r)^2 = P_j^r. \quad (2.16)$$

In fact, more generally, we have the property

$$P_{j'}^{r'} P_j^r = P_j^r P_{j'}^{r'} = P_j^r, \quad \text{if } 0 \leq j' - j \leq r - r'. \quad (2.17)$$

A useful case of this is $r' = 3$, from which we have

$$e_{j'} P_j^r = P_j^r e_{j'} = 0, \quad \text{if } j \leq j' \leq j + r - 3. \quad (2.18)$$

The fusion operators also satisfy the Hecke-like identity

$$S_{r-1}^2 P_{j+1}^r P_j^r P_{j+1}^r - P_{j+1}^r = S_{r-1}^2 P_j^r P_{j+1}^r P_j^r - P_j^r = S_{r-2} S_r P_j^{r+1}. \quad (2.19)$$

2.4 Fused Row Operators

We now introduce operators $Y_j^r(u)$ and $\tilde{Y}_j^r(u)$, for $r \in \{1, \dots, \min(g-1, L+1)\}$ and $j \in \{1, \dots, L+2-r\}$, which correspond to fused rows of faces. These operators are

related to products of $r-1$ face operators, for $r \geq 2$, by

$$\begin{aligned}
\prod_{k=1}^{r-2} s_k(-u) Y_j^r(u) &= P_{j+1}^r X_j(u-(r-2)\lambda) \dots X_{j+r-3}(u-\lambda) X_{j+r-2}(u) \\
&= X_j(u) X_{j+1}(u-\lambda) \dots X_{j+r-2}(u-(r-2)\lambda) P_j^r
\end{aligned}$$
(2.20a)

and

$$\begin{aligned}
\prod_{k=0}^{r-3} s_{-k}(-u) \tilde{Y}_j^r(u) &= P_j^r X_{j+r-2}(u) X_{j+r-3}(u+\lambda) \dots X_j(u+(r-2)\lambda) \\
&= X_{j+r-2}(u+(r-2)\lambda) \dots X_{j+1}(u+\lambda) X_j(u) P_{j+1}^r
\end{aligned}$$
(2.20b)

The second (or fourth) equalities in (2.20) imply the push-through relations

$$\begin{aligned}
Y_j^r(u) &= P_{j+1}^r Y_j^r(u) = Y_j^r(u) P_j^r \\
\tilde{Y}_j^r(u) &= P_j^r \tilde{Y}_j^r(u) = \tilde{Y}_j^r(u) P_{j+1}^r,
\end{aligned}
\tag{2.21}$$

and can be derived using (2.15) and repeated application of (2.8).

The fused row operators can be written in terms of fusion operators as

$$\begin{aligned}
Y_j^r(u) &= S_{r-1} s_1(u) P_{j+1}^r P_j^r - S_r s_0(u) P_j^{r+1} \\
\tilde{Y}_j^r(u) &= S_{r-1} s_{r-1}(u) P_j^r P_{j+1}^r - S_r s_{r-2}(u) P_j^{r+1}.
\end{aligned}
\tag{2.22}$$

The equivalence of (2.20) and (2.22) follows from several of the properties of fusion operators listed in Section 2.3.

We note, as examples, that for the first two fusion levels,

$$Y_j^1(u) = -s_0(u) I, \quad \tilde{Y}_j^1(u) = s_1(-u) I, \quad Y_j^2(u) = \tilde{Y}_j^2(u) = X_j(u). \quad (2.23)$$

An important property of the fused row operators is that they satisfy the mixed Yang-Baxter equations,

$$X_j(u-v) Y_{j+1}^r(u) Y_j^r(v) = Y_{j+1}^r(v) Y_j^r(u) X_{j+r-1}(u-v) \quad (2.24)$$

$$X_{j+r-1}(u-v) \tilde{Y}_j^r(u) \tilde{Y}_{j+1}^r(v) = \tilde{Y}_j^r(v) \tilde{Y}_{j+1}^r(u) X_j(u-v) \quad (2.25)$$

$$Y_j^r(u) X_{j+r-1}(u+v) \tilde{Y}_j^r(v) = \tilde{Y}_{j+1}^r(v) X_j(u+v) Y_{j+1}^r(u). \quad (2.26)$$

These equations can be obtained using (2.20) and repeated application of (2.8).

The fused row operators also satisfy the product identities

$$\begin{aligned} Y_j^r(u) \tilde{Y}_j^r(v) &= s_1(u) s_{r-1}(v) P_{j+1}^r - S_r s_0(u+v) P_j^{r+1} \\ \tilde{Y}_j^r(u) Y_j^r(v) &= s_{r-1}(u) s_1(v) P_j^r - S_r s_0(u+v) P_j^{r+1}, \end{aligned} \quad (2.27)$$

these being most easily derived using (2.22) and properties of the fusion operators.

2.5 Boundary Operators

We now introduce boundary operators $K_j^r(u, \xi)$, with $\xi \in \mathbb{C}$, as products of two fused row operators,

$$K_j^r(u, \xi) = -Y_j^r(u - \lambda - \xi) \tilde{Y}_j^r(u + \lambda + \xi). \quad (2.28)$$

These operators correspond in a lattice model to boundary Boltzmann weights and in this context ξ is a boundary field parameter.

From (2.27), we see that the boundary operators can be written in terms of fusion operators as

$$K_j^r(u, \xi) = s_0(\xi - u) s_r(\xi + u) P_{j+1}^r + S_r s_0(2u) P_j^{r+1}. \quad (2.29)$$

An alternative expression, which follows using (2.12) on the second term on the right side of (2.29), is

$$K_j^r(u, \xi) = s_0(\xi+u) s_r(\xi-u) P_j^{r+1} + \frac{S_{r-1}}{S_r} s_0(\xi-u) s_r(\xi+u) P_{j+1}^r e_j P_{j+1}^r. \quad (2.30)$$

We see, as examples, that for the first two fusion levels,

$$K_j^1(u, \xi) = s_0(\xi+u) s_1(\xi-u) I, \quad K_j^2(u, \xi) = s_0(\xi+u) s_2(\xi-u) I - s_0(2u) e_j. \quad (2.31)$$

The key property of the face and boundary operators is that they satisfy the operator form of the boundary Yang-Baxter equation,

$$\begin{aligned} X_j(u-v) K_{j+1}^r(u, \xi) X_j(u+v) K_{j+1}^r(v, \xi) = \\ K_{j+1}^r(v, \xi) X_j(u+v) K_{j+1}^r(u, \xi) X_j(u-v). \end{aligned} \quad (2.32)$$

This can be proved by substituting (2.28) into the left side of (2.32), using (2.26) followed by (2.24) to bring $X_{j+r-1}(u-v)$ adjacent to $X_{j+r-1}(u+v)$, interchanging the order of these face operators using (2.9), and then using (2.25) followed by (2.26) to give the right side of (2.32).

In terms of the construction procedure of [4], the boundary operators $K_j^r(u, \xi)$ can be considered as a family of solutions, one solution for each value of r , of (2.32) with given $X_j(u)$, these solutions having been constructed by starting with the identity solution of (2.32) and adding a fused double row of faces of width $r-1$.

The boundary operators also satisfy the operator form of the boundary inversion relation,

$$K_j^r(u, \xi) K_j^r(-u, \xi) = s_0(\xi-u) s_0(\xi+u) s_r(\xi-u) s_r(\xi+u) P_{j+1}^r, \quad (2.33)$$

this being most easily obtained using (2.29) and properties of the fusion operators.

3. Lattice Models Based on Graphs

In this section, we consider representations of the Temperley-Lieb algebra involving a graph and the associated graph-based lattice models. Our general treatment is motivated by that introduced in [10, 30] and, when considering fusion for these models, our approach is also motivated by certain results of [41, 42, 43, 44].

A graph-based lattice model of the type to be considered here can be associated with any pair \mathcal{G} and ψ , where \mathcal{G} is a connected graph containing only unoriented, single edges and ψ is an eigenvector of the adjacency matrix of \mathcal{G} with all nonzero entries. All of the formalism and results of Section 3 are applicable to any choice of \mathcal{G} and ψ , and only in Section 4 will we eventually specialize \mathcal{G} to be an A , D or E Dynkin diagram and ψ to be the Perron-Frobenius eigenvector of its adjacency matrix, thus giving the critical unitary A – D – E models.

In a lattice model based on \mathcal{G} , a spin is attached to each site of a two-dimensional square lattice, with the possible states of each spin being the nodes of \mathcal{G} and there being a lattice adjacency condition stipulating that, in any assignment of spin states to the lattice, the states on each pair of nearest-neighbor sites must correspond to an edge of \mathcal{G} . These models are interaction-round-a-face models, so that a bulk Boltzmann weight is associated with each set of four spin states adjacent around a square face. Here, we shall also obtain and use sets of boundary weights, each of these weights being associated with three adjacent spin states. The partition function of the model on a cylinder is then the sum, over all possible spin assignments, of products of Boltzmann weights, with each square face in the bulk of the lattice contributing a bulk weight and each alternate triplet of neighboring sites on the boundaries contributing a boundary weight.

The key property of the boundary weights obtained in this section is that they satisfy the boundary Yang-Baxter equation for interaction-round-a-face models. This equation was first used in [33, 45] and is based on the reflection equation introduced in [46]. However, we note that the boundary weights obtained here depend on certain additional fusion indices, which gives them and the boundary Yang-Baxter equation they satisfy a somewhat more general form than the form of those used in

all previous studies. We shall show that a further important property of the three-spin boundary weights used here is that, at a certain point, they simultaneously decompose into more natural two-spin boundary edge weights.

Finally, using these and other local properties of the bulk and boundary weights, we shall identify various symmetry properties of the partition function and transfer matrices, including the invariance of the partition function under interchanging parts or all of the left and right boundaries, and the facts that the transfer matrices form a commuting family and, in certain cases, have all nonnegative eigenvalues.

3.1 Graphs and Paths

Throughout Section 3, we shall be considering a finite graph \mathcal{G} with an associated adjacency matrix G . We require that \mathcal{G} contain only unoriented, single edges, implying that G is symmetric and that each of its nonzero entries is 1. In fact, the formalism of Section 3 can be generalized straightforwardly to encompass graphs with multiple edges, but since this is not needed for the A – D – E cases of primary interest, we shall for simplicity restrict our attention to graphs with only single edges.

We also require that \mathcal{G} be connected, implying that G is indecomposable. Perron-Frobenius theory then implies that G has a unique maximum eigenvalue with an associated eigenvector whose entries are all positive.

We shall denote the set of all r -point paths on \mathcal{G} , for $r \in \mathbb{Z}_{\geq 1}$, by \mathcal{G}^r ; that is,

$$\mathcal{G}^r = \left\{ (a_0, \dots, a_{r-1}) \mid a_j \in \mathcal{G}, \prod_{j=0}^{r-2} G_{a_j a_{j+1}} = 1 \right\}. \quad (3.1)$$

We note that \mathcal{G}^1 corresponds to the set of nodes of \mathcal{G} and that \mathcal{G}^2 is the set of edges of \mathcal{G} .

We shall also denote the set of all r -point paths between a and b in \mathcal{G} by \mathcal{G}_{ab}^r ; that is,

$$\mathcal{G}_{ab}^r = \left\{ (a_0, \dots, a_{r-1}) \in \mathcal{G}^r \mid a_0 = a, a_{r-1} = b \right\}. \quad (3.2)$$

It follows that

$$|\mathcal{G}_{ab}^r| = (G^{r-1})_{ab}. \quad (3.3)$$

3.2 Graph Representations of the Temperley-Lieb Algebra

A graph representation involving \mathcal{G} of the Temperley-Lieb algebra $\mathcal{T}(L, \lambda)$ exists for each λ for which $2 \cos \lambda$ is an eigenvalue of G with an associated eigenvector ψ whose entries are all nonzero; that is, for each λ for which there exists a vector ψ satisfying

$$\sum_{b \in \mathcal{G}} G_{ab} \psi_b = 2 \cos \lambda \psi_a \quad \text{and} \quad \psi_a \neq 0, \quad \text{for each } a \in \mathcal{G}. \quad (3.4)$$

There is always at least one such case, namely that provided by the Perron-Frobenius eigenvector and eigenvalue. We shall assume, throughout the rest of Section 3, that a fixed choice of λ and ψ has been made. We note that, since G is symmetric, $\cos \lambda$ must be real so that each ψ_a can, and will, be assumed to be real. In the rest of this paper, we shall often use $\psi_a^{1/2}$ and $\psi_a^{1/4}$, which we take to be positive for positive ψ_a or to have arguments $\pi/2$ and $\pi/4$ respectively for negative ψ_a .

The elements of the representation of $\mathcal{T}(L, \lambda)$ associated with \mathcal{G} and ψ are matrices with rows and columns labeled by the paths of \mathcal{G}^{L+2} , with the generators e_j being defined by

$$e_j (a_0, \dots, a_{L+1}), (b_0, \dots, b_{L+1}) = \frac{\psi_{a_j}^{1/2} \psi_{b_j}^{1/2}}{\psi_{a_{j-1}}} \delta_{a_{j-1} a_{j+1}} \prod_{\substack{k=0 \\ k \neq j}}^{L+1} \delta_{a_k b_k}. \quad (3.5)$$

It follows straightforwardly that the defining relations (2.1) of $\mathcal{T}(L, \lambda)$ are satisfied, with the first relation depending on (3.4).

3.3 Bulk Weights

We now proceed to a consideration of the lattice model based on the graph \mathcal{G} and associated with the adjacency matrix eigenvector ψ .

The bulk weights for this model are given explicitly, for each $(a, b, c, d, u) \in \mathcal{G}^5$, by

$$W \left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array} \right) = s_1(-u) \delta_{ac} + \frac{s_0(u) \psi_a^{1/2} \psi_c^{1/2}}{\psi_b} \delta_{bd}, \quad (3.6)$$

where u is the spectral parameter and λ , on which s depends through (2.2), is the crossing parameter. The spectral parameter can be considered as a measure

of anisotropy, with $u = \lambda/2$ being an isotropic point and $u = 0$ and $u = \lambda$ being completely anisotropic points. We note that the number of bulk weights is $\text{tr}(G^4)$.

We shall represent the bulk weights diagrammatically as

$$W\left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array}\right) = \begin{array}{c} \begin{array}{ccc} d & & c \\ & \square & \\ a & & b \end{array} \\ \swarrow \end{array} . \quad (3.7)$$

These bulk weights are related to the face operators (2.6) by

$$W\left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array}\right) = X_j(u)_{(e_0, \dots, e_{j-2}, d, a, b, e_{j+2}, \dots, e_{L+1}), (e_0, \dots, e_{j-2}, d, c, b, e_{j+2}, \dots, e_{L+1})} , \quad (3.8)$$

where $X_j(u)$ is taken in the graph representation of $\mathcal{T}(L, \lambda)$.

We see that the bulk weights satisfy reflection symmetry,

$$W\left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array}\right) = W\left(\begin{array}{cc|c} d & a & u \\ c & b & \end{array}\right) = W\left(\begin{array}{cc|c} b & c & u \\ a & d & \end{array}\right) , \quad (3.9)$$

crossing symmetry,

$$W\left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array}\right) = \frac{\psi_a^{1/2} \psi_c^{1/2}}{\psi_b^{1/2} \psi_d^{1/2}} W\left(\begin{array}{cc|c} c & d & \lambda - u \\ b & a & \end{array}\right) , \quad (3.10)$$

and the anisotropy property

$$W\left(\begin{array}{cc|c} d & c & 0 \\ a & b & \end{array}\right) = \delta_{ac} . \quad (3.11)$$

It follows from (2.8), (2.10) and (3.8) that the bulk weights also satisfy the Yang-Baxter equation,

$$\sum_{\substack{g \in \mathcal{G} \\ (G_{bg} G_{dg} G_{fg} = 1)}} W\left(\begin{array}{cc|c} f & g & u-v \\ a & b & \end{array}\right) W\left(\begin{array}{cc|c} g & d & u \\ b & c & \end{array}\right) W\left(\begin{array}{cc|c} f & e & v \\ g & d & \end{array}\right) = \\ \sum_{\substack{g \in \mathcal{G} \\ (G_{ag} G_{cg} G_{eg} = 1)}} W\left(\begin{array}{cc|c} a & g & v \\ b & c & \end{array}\right) W\left(\begin{array}{cc|c} f & e & u \\ a & g & \end{array}\right) W\left(\begin{array}{cc|c} e & d & u-v \\ g & c & \end{array}\right) \quad (3.12)$$

for each $(a, b, c, d, e, f, a) \in \mathcal{G}^7$, and the inversion relation

$$\sum_{\substack{e \in \mathcal{G} \\ (G_{be} G_{de} = 1)}} W \left(\begin{array}{cc|c} d & e & -u \\ a & b & \end{array} \right) W \left(\begin{array}{cc|c} d & c & u \\ e & b & \end{array} \right) = \begin{array}{c} \begin{array}{c} d \quad \cdots \quad d \\ \diagdown \quad \diagup \\ \quad \bullet \\ \diagup \quad \diagdown \\ b \quad \cdots \quad b \end{array} \end{array} \quad (3.13)$$

$$= s_1(u) s_1(-u) \delta_{ac},$$

for each $(a, b, c, d, a) \in \mathcal{G}^5$. In these and all subsequent diagrams, solid circles are used to indicate spins whose states are summed over and dotted lines are used to connect identical spins.

3.4 Fusion

We now consider various objects related to the process of fusion in graph-based lattice models.

3.4.1 Maximum Fusion Level

Having chosen a graph \mathcal{G} and an adjacency matrix eigenvector with eigenvalue $2 \cos \lambda$, the maximum fusion level g is then determined by λ according to (2.11). We note that although λ itself is only determined by the eigenvector up to sign and shifts of 2π , such changes in λ do not affect g or any other properties of interest.

As we shall see in more detail in Section 4.1, if \mathcal{G} is an A , D or E Dynkin diagram, then g is the Coxeter number of \mathcal{G} , since any eigenvector of G with all nonzero entries has an eigenvalue $2 \cos(k\pi/h)$, where $h \in \mathbb{Z}_{\geq 2}$ is the Coxeter number of \mathcal{G} and $k \in \{1, \dots, h-1\}$ is a Coxeter exponent coprime to h .

Although the A – D – E cases are of primary interest, simply as a further example, we briefly discuss the $A^{(1)}$, $D^{(1)}$ and $E^{(1)}$ Dynkin diagrams of the affine Lie algebras. If \mathcal{G} is one of these graphs, then any eigenvalue of G can be written as $2 \cos(k\pi/h)$, where h is the Coxeter number of \mathcal{G} and $k \in \{0, \dots, h\}$ is a Coxeter exponent. For all of these graphs, $k = 0$ is a Coxeter exponent, giving a maximal eigenvalue of 2, and in some cases $k = h$ is also a Coxeter exponent, giving a minimal eigenvalue of -2 , so if either of these eigenvalues is chosen, then $g = \infty$ (and, incidentally, the

second case of (2.2) applies). However, if an eigenvalue corresponding to a Coxeter exponent $0 < k < h$ is chosen, then g is finite with $g \leq h$.

3.4.2 Fusion Matrices

We now introduce, for each $r \in \{1, \dots, g\}$ and $a, b \in \mathcal{G}$ satisfying $(G^{r-1})_{ab} > 0$, a fusion matrix $P^r(a, b)$ with rows and columns labeled by the paths of \mathcal{G}_{ab}^r and entries given by

$$P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)} = \begin{cases} 1, & r = 1 \\ P_1^r(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b), & r = 2, \dots, g, \end{cases} \quad (3.14)$$

where the fusion operator P_1^r is defined by (2.12) and taken in the graph representation of $\mathcal{T}(r-2, \lambda)$.

It follows from (2.16) that each fusion matrix is a projector,

$$P^r(a, b)^2 = P^r(a, b). \quad (3.15)$$

It also follows, from (2.12), (3.8) and the first equality of (3.9), that each fusion matrix is symmetric,

$$P^r(a, b)^T = P^r(a, b) \quad (3.16)$$

and, from (2.15) and (3.8), that a and b can be interchanged according to

$$P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)} = P^r(b, a)_{(b, c_{r-2}, \dots, c_1, a), (b, d_{r-2}, \dots, d_1, a)}. \quad (3.17)$$

We note that the fusion matrices also satisfy more general projection-type relations corresponding to those, (2.17), satisfied by the fusion operators.

3.4.3 Fused Adjacency Matrices

We next introduce fused adjacency matrices, F^1, \dots, F^g , which are defined by the $\hat{s}\ell(2)$ recursion,

$$F^1 = I; \quad F^2 = G; \quad F^r = G F^{r-1} - F^{r-2}, \quad r = 3, \dots, g. \quad (3.18)$$

We see that each fused adjacency matrix is a polynomial in G and hence that the set of these matrices is mutually commuting. In fact, the polynomial form is given by the Type II Chebyshev polynomials \mathcal{U}_r ,

$$F^r = \mathcal{U}_{r-1}(G/2). \quad (3.19)$$

We note that at various places in Section 4, we shall be considering the fused adjacency matrices of two different graphs and in these cases we shall explicitly indicate the dependence on the graph as $F(\mathcal{G})^r$.

The main relevance of the fused adjacency matrices at this point is that their entries give the ranks of the fusion matrices, according to

$$F_{ab}^r = \begin{cases} 0, & (G^{r-1})_{ab} = 0 \\ \text{rank } P^r(a, b), & (G^{r-1})_{ab} > 0. \end{cases} \quad (3.20)$$

This result can be proved by defining matrices \tilde{F}^r with entries \tilde{F}_{ab}^r given by the right side of (3.20) and showing that these matrices satisfy relations (3.18), so that $\tilde{F}^r = F^r$. Showing that \tilde{F}^r satisfy the initial conditions of (3.18) is straightforward. Meanwhile, showing that \tilde{F}^r satisfy the recursion relation of (3.18) can be done by using the fact that the rank of any projector is given by its trace (since by idempotence each eigenvalue is either 0 or 1, the rank is the number of eigenvalues which are 1 and the trace is the sum of eigenvalues) and then using definitions (2.6), (3.5) and (3.14), the recursion relation of (2.12), which is needed twice, relations (2.16) and (3.4), and general properties of the trace and of the numbers S_r .

We note that (3.20) also implies that F_{ab}^r are nonnegative integers. In fact, the property that the entries of F^r are integers follows immediately from the properties that the entries of G are integers and that each F^r is a polynomial, with integer coefficients, in G , but the property that the entries of F^r are also nonnegative is less trivial and depends on the restriction $r \leq g$ and on some of the additionally-assumed properties of G , such as its being symmetric. Since the result of nonnegativity is of some interest in its own right, we note that (3.20) specifically implies that if G is any symmetric indecomposable matrix with each entry in $\{0, 1\}$ and if F^r is defined in terms of G by (3.19), then each entry of F^r is a nonnegative integer for

any $r \in \{1, \dots, g_{\max}\}$, where g_{\max} is the largest of the values g corresponding to the eigenvectors of G with all nonzero entries.

3.4.4 Fusion Vectors

It can be shown using standard results of linear algebra that any symmetric idempotent matrix $P = P^T = P^2$ with complex entries can be orthonormally diagonalized; that is, written as $P = U D U^{-1}$, where the matrix of eigenvectors U satisfies $U^{-1} = U^T$ and D has rank P 1's on the diagonal and all other entries 0. We note that if $P = P^*$ then this simply amounts to an orthonormal diagonalization of a real symmetric matrix, but that if $P \neq P^*$ then it differs from a unitary diagonalization and that, in fact, P is then not normal and a unitary diagonalization is not possible.

From this result, it follows that each fusion matrix $P^r(a, b)$ can be decomposed using F_{ab}^r orthonormal eigenvectors with eigenvalue 1. We shall denote, for $r \in \{1, \dots, g\}$ and $a, b \in \mathcal{G}$ satisfying $F_{ab}^r > 0$, such eigenvectors as $U^r(a, b)_\alpha$, where $\alpha = 1, \dots, F_{ab}^r$, and refer to these as fusion vectors.

The decomposition and orthonormality are then

$$\sum_{\alpha=1}^{F_{ab}^r} U^r(a, b)_\alpha U^r(a, b)_\alpha^T = P^r(a, b) \quad (3.21)$$

and

$$U^r(a, b)_\alpha^T U^r(a, b)_{\alpha'} = \delta_{\alpha\alpha'}, \quad (3.22)$$

or, more explicitly,

$$\sum_{\alpha=1}^{F_{ab}^r} U^r(a, b)_{\alpha, (a, c_1, \dots, c_{r-2}, b)} U^r(a, b)_{\alpha, (a, d_1, \dots, d_{r-2}, b)} = P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)}$$

and

$$\sum_{(a, c_1, \dots, c_{r-2}, b) \in \mathcal{G}_{ab}^r} U^r(a, b)_{\alpha, (a, c_1, \dots, c_{r-2}, b)} U^r(a, b)_{\alpha', (a, c_1, \dots, c_{r-2}, b)} = \delta_{\alpha\alpha'}.$$

We note, as examples, that for the first two fusion levels,

$$P^1(a, a)_{(a), (a)} = \pm U^1(a, a)_{1, (a)} = 1, \quad \text{for each } a \in \mathcal{G}, \quad (3.23)$$

and

$$P^2(a, b)_{(a,b),(a,b)} = \pm U^2(a, b)_{1,(a,b)} = 1, \quad \text{for each } (a, b) \in \mathcal{G}^2. \quad (3.24)$$

We shall assume that a specific choice of $U^r(a, b)_\alpha$ has been made. All other possible choices are then given by transformations,

$$U^r(a, b)_\alpha \mapsto \sum_{\alpha'=1}^{F_{ab}^r} R^r(a, b)_{\alpha\alpha'} U^r(a, b)_{\alpha'}, \quad (3.25)$$

where $R^r(a, b)$ is an orthonormal matrix,

$$\sum_{\alpha''=1}^{F_{ab}^r} R^r(a, b)_{\alpha\alpha''} R^r(a, b)_{\alpha'\alpha''} = \delta_{\alpha\alpha'}. \quad (3.26)$$

We shall see that all of the lattice model properties of interest will be invariant under such transformations and thus independent of the choice of fusion vectors.

3.5 Boundary Weights

We now use the boundary operators (2.28) to obtain a set of boundary Boltzmann weights for the lattice model for each pair (r, a) , where $r \in \{1, \dots, g-1\}$ is a fusion level and a is a node of \mathcal{G} . It is thus natural to regard these pairs as labeling the boundary conditions,

$$\{\text{boundary conditions}\} \longleftrightarrow \{(r, a) \mid r \in \{1, \dots, g-1\}, a \in \mathcal{G}\}. \quad (3.27)$$

The (r, a) boundary weights are given, for each $(b, c, d) \in \mathcal{G}^3$ with $F_{ba}^r F_{da}^r > 0$ and $\beta \in \{1, \dots, F_{ba}^r\}$, $\delta \in \{1, \dots, F_{da}^r\}$, by

$$B^{ra} \left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi \right) = \frac{\psi_c^{1/2}}{s_0(2\xi) \psi_b^{1/4} \psi_d^{1/4}} \sum_{\substack{(b, e_1, \dots, e_{r-2}, a) \in \mathcal{G}_{ba}^r \\ (d, f_1, \dots, f_{r-2}, a) \in \mathcal{G}_{da}^r}} U^r(b, a)_{\beta, (b, e_1, \dots, e_{r-2}, a)} U^r(d, a)_{\delta, (d, f_1, \dots, f_{r-2}, a)} \times K_1^r(u, \xi)_{(c, b, e_1, \dots, e_{r-2}, a), (c, d, f_1, \dots, f_{r-2}, a)}, \quad (3.28)$$

where $K_1^T(u, \xi)$ is taken in the graph representation of $\mathcal{T}(r-1, \lambda)$ and ξ corresponds to a boundary field. We shall represent the boundary weights diagrammatically as

$$B^{ra} \left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi \right) = c \begin{array}{c} \begin{array}{c} d \quad \delta \\ \diagup \quad \diagdown \\ r, a \\ u, \xi \\ \diagdown \quad \diagup \\ b \quad \beta \end{array} \end{array}. \quad (3.29)$$

We see that

$$\text{number of } (r, a) \text{ boundary weights} = ((F^r)^2 G^2)_{aa}. \quad (3.30)$$

We shall refer to a boundary weight (3.28) as being of diagonal type if $b = d$ and $\beta = \delta$ and as being of nondiagonal type otherwise, and we note that in the majority of previous studies involving such boundary weights, only diagonal weights were considered.

We also note, as an example, that the $(1, a)$ boundary weights are all diagonal and given by

$$B^{1a} \left(c \begin{array}{cc} a & 1 \\ a & 1 \end{array} \middle| u, \xi \right) = \frac{s_0(\xi+u) s_1(\xi-u) \psi_c^{1/2}}{s_0(2\xi) \psi_a^{1/2}}. \quad (3.31)$$

A $(1, a)$ boundary condition is thus one in which the state of every alternate boundary spin is fixed to be a , while each other boundary spin, whose state can be any c adjacent to a on \mathcal{G} , is associated with a weight proportional to $\psi_c^{1/2}$. We shall refer to such a boundary condition, in which the state of every alternate boundary spin is fixed, as semi-fixed.

We now find that the boundary weights can also be expressed as

$$B^{ra} \left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi \right) = - \left(s_0(2\xi) \prod_{k=1}^{r-2} s_{-k-1}(u-\xi) s_k(u+\xi) \right)^{-1} \times$$

$$\frac{\psi_d^{1/4} \psi_g^{1/2}}{\psi_b^{1/4} \psi_a^{1/2}} \begin{array}{c} U^r(d, a)_{\delta, (d, f_1, f_2, \dots, f_{r-2}, a)} \\ \begin{array}{c} \begin{array}{c} d \quad f_1 \quad f_2 \quad \dots \quad f_{r-2} \quad a \\ \hline \begin{array}{c} -u-\xi \\ -(r-2)\lambda \end{array} \quad \begin{array}{c} -u-\xi \\ -(r-3)\lambda \end{array} \quad \dots \quad \begin{array}{c} -u-\xi \\ \end{array} \\ c \quad \hline \begin{array}{c} u-\xi \\ -(r-1)\lambda \end{array} \quad \begin{array}{c} u-\xi \\ -(r-2)\lambda \end{array} \quad \dots \quad \begin{array}{c} u-\xi-\lambda \\ \end{array} \\ b \quad e_1 \quad e_2 \quad \dots \quad e_{r-2} \quad a \end{array} \\ \hline U^r(b, a)_{\beta, (b, e_1, e_2, \dots, e_{r-2}, a)} \end{array} \end{array}, \quad (3.32)$$

the orientation of the central bulk weights on each side of (3.33) can be changed to that required for (2.32) by using crossing symmetry (3.10), with the eigenvector entries from (3.10) canceling where needed with those introduced explicitly through (3.28).

We note that the boundary Yang-Baxter equation (3.33) is still satisfied after renormalization of the boundary weights,

$$B^{ra}\left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi\right) \mapsto f^{ra}(u, \xi) B^{ra}\left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi\right), \quad (3.34)$$

where f^{ra} are arbitrary functions. It is also still satisfied after gauge transformations of the boundary weights,

$$B^{ra}\left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi\right) \mapsto \sum_{\beta'=1}^{F_{ba}^r} \sum_{\delta'=1}^{F_{da}^r} S^{ra}(b)_{\beta\beta'} S^{ra}(d)_{\delta\delta'} B^{ra}\left(c \begin{array}{cc} d & \delta' \\ b & \beta' \end{array} \middle| u, \xi\right), \quad (3.35)$$

where $S^{ra}(e)$ are arbitrary orthonormal matrices,

$$\sum_{\alpha''=1}^{F_{ea}^r} S^{ra}(e)_{\alpha\alpha''} S^{ra}(e)_{\alpha'\alpha''} = \delta_{\alpha\alpha'}. \quad (3.36)$$

Indeed, a transformation (3.25) of the fusion vectors simply induces a gauge transformation of the boundary weights with

$$S^{ra}(e) = R^r(e, a). \quad (3.37)$$

In addition to the boundary Yang-Baxter equation, some other important local relations satisfied by the boundary weights are boundary reflection symmetry,

$$B^{ra}\left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi\right) = B^{ra}\left(c \begin{array}{cc} b & \beta \\ d & \delta \end{array} \middle| u, \xi\right), \quad (3.38)$$

boundary crossing symmetry,

$$\begin{aligned} \sum_{(b,e,d) \in \mathcal{G}_{bd}^3} W\left(\begin{array}{cc} d & e \\ c & b \end{array} \middle| 2u - \lambda\right) B^{ra}\left(e \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| u, \xi\right) \\ = s_0(2u) B^{ra}\left(c \begin{array}{cc} d & \delta \\ b & \beta \end{array} \middle| \lambda - u, \xi\right), \end{aligned} \quad (3.39)$$

and the boundary inversion relation,

$$\sum_{\substack{e \in \mathcal{G} \\ (G_{ce} F_{ea}^r > 0)}} \sum_{\gamma=1}^{F_{ea}^r} \frac{\psi_b^{1/4} \psi_d^{1/4} \psi_e^{1/2}}{\psi_c} B^{ra} \left(c \begin{array}{c} e \\ b \end{array} \begin{array}{c} \gamma \\ \beta \end{array} \middle| u, \xi \right) B^{ra} \left(c \begin{array}{c} d \\ e \end{array} \begin{array}{c} \delta \\ \gamma \end{array} \middle| -u, \xi \right) \quad (3.40)$$

$$= \frac{s_0(\xi - u) s_0(\xi + u) s_r(\xi - u) s_r(\xi + u)}{s_0(2\xi)^2} \delta_{bd} \delta_{\beta\delta},$$

for each $(b, c, d) \in \mathcal{G}^3$ with $F_{ba}^r F_{da}^r > 0$ and $\beta \in \{1, \dots, F_{ba}^r\}$, $\delta \in \{1, \dots, F_{da}^r\}$. Boundary reflection symmetry follows from (3.28), boundary crossing symmetry can be proved by expressing the boundary weights in (3.39) in the form (3.32) and repeatedly applying the Yang-Baxter equation (3.12), and the boundary inversion relation follows from the operator form of the boundary inversion relation, (2.33).

3.6 Boundary Edge Weights

We now introduce boundary edge weights in terms of which the boundary weights of the previous section can be expressed.

We begin by defining, for each boundary condition (r, a) , a set of boundary edges as

$$\mathcal{E}^{ra} = \{(b, c) \in \mathcal{G}^2 \mid F_{ba}^r F_{ca}^{r+1} > 0\}. \quad (3.41)$$

We note that the boundary edges are ordered pairs and that, in contrast to the graph's set of edges for which $(b, c) \in \mathcal{G}^2 \Leftrightarrow (c, b) \in \mathcal{G}^2$, the appearance of (b, c) in \mathcal{E}^{ra} need not imply the appearance of (c, b) in \mathcal{E}^{ra} .

The (r, a) boundary edge weights are now given, for each $(b, c) \in \mathcal{E}^{ra}$, $\beta \in \{1, \dots, F_{ba}^r\}$ and $\gamma \in \{1, \dots, F_{ca}^{r+1}\}$, by

$$E^{ra}(b, c)_{\beta\gamma} = \frac{S_r^{1/2} \psi_c^{1/4}}{\psi_b^{1/4}} \sum_{(b, d_1, \dots, d_{r-2}, a) \in \mathcal{G}_{ba}^r} U^r(b, a)_{\beta, (b, d_1, \dots, d_{r-2}, a)} U^{r+1}(c, a)_{\gamma, (c, b, d_1, \dots, d_{r-2}, a)}. \quad (3.42)$$

We shall represent the boundary edge weights diagrammatically as

$$E^{ra}(b, c)_{\beta\gamma} = \begin{array}{c} c \quad \quad \gamma \\ \quad \diagdown \quad \diagup \\ \quad \quad r, a \\ \quad \diagup \quad \diagdown \\ b \quad \quad \beta \end{array}. \quad (3.43)$$

We see that

$$\text{number of } (r, a) \text{ boundary edge weights} = (F^r G F^{r+1})_{aa}. \quad (3.44)$$

We note, as an example, that for the $(1, a)$ boundary condition,

$$\mathcal{E}^{1a} = \{(a, c) \mid G_{ac} = 1\}, \quad E^{1a}(a, c)_{11} = \pm \psi_c^{1/4} / \psi_a^{1/4}. \quad (3.45)$$

We now find, substituting (2.29) into (3.28) and using (3.14), (3.21) and (3.22), a general expression for the boundary weights in terms of boundary edge weights,

$$B^{ra} \left(c \begin{array}{c} d \quad \delta \\ b \quad \beta \end{array} \middle| u, \xi \right) = \frac{s_0(\xi - u) s_r(\xi + u) \psi_c^{1/2}}{s_0(2\xi) \psi_b^{1/2}} \delta_{bd} \delta_{\beta\delta} + \frac{s_0(2u)}{s_0(2\xi)} \sum_{\gamma=1}^{F_{ca}^{r+1}} E^{ra}(b, c)_{\beta\gamma} E^{ra}(d, c)_{\delta\gamma}. \quad (3.46)$$

From this, we immediately see that at $u = \xi$ the boundary weights are independent of ξ and can be decomposed as a sum of products of boundary edge weights,

$$B^{ra} \left(c \begin{array}{c} d \quad \delta \\ b \quad \beta \end{array} \middle| \xi, \xi \right) = \sum_{\gamma=1}^{F_{ca}^{r+1}} E^{ra}(b, c)_{\beta\gamma} E^{ra}(d, c)_{\delta\gamma} \quad (3.47)$$

We note that the origin of this decomposition is the fact, apparent from (2.29), that at $u = \xi$ the boundary operators are proportional to fusion operators, so that the decomposition of boundary weights is essentially equivalent to the eigenvector decomposition of projectors.

We shall refer to this point, $u = \xi$, as the conformal point, since it is here that certain lattice models are expected to exhibit conformal behavior, with the set of (r, a) boundary edge weights providing a lattice realization of a particular conformal boundary condition.

We find, by using (2.30) in (3.28), that a decomposition similar to (3.47) also occurs at $u = -\xi$,

$$B^{ra} \left(c \begin{array}{c} d \ \delta \\ b \ \beta \end{array} \middle| -\xi, \xi \right) = \sum_{\substack{\gamma=1 \\ (r \neq 1)}}^{F_{ca}^{r-1}} E^{r-1,a}(c, b)_{\gamma\beta} E^{r-1,a}(c, d)_{\gamma\delta}. \quad (3.48)$$

We therefore see that, apart from an unimportant reversal of the order of the nodes in the boundary edges, the (r, a) boundary condition at $u = -\xi$ is equivalent to the $(r-1, a)$ boundary condition at $u = \xi$. In fact, decompositions of the form (3.47) or (3.48) also occur at other points, for example at $u = -r\lambda - \xi$, $u = r\lambda + \xi$ or points related to these by trigonometric periodicity, but since these points all involve the same boundary edge weights up to reordering of the nodes in the boundary edges or relabeling of r as $r \pm 1$, we can, without loss of generality, restrict our attention to the single conformal point $u = \xi$.

We also note that the sum in (3.47) is empty if $F_{ca}^{r+1} = 0$. It is thus possible that for a particular boundary condition, certain boundary weights are non-zero away from the conformal point but vanish at the conformal point. From (3.46), we find that such boundary weights are specifically those for which $b = d$, $\beta = \delta$, $F_{ba}^r G_{bc} > 0$ and $F_{ca}^{r+1} = 0$.

We see from (3.46) that the boundary weights satisfy the boundary anisotropy property

$$B^{ra} \left(c \begin{array}{c} d \ \delta \\ b \ \beta \end{array} \middle| 0, \xi \right) = \frac{s_0(\xi) s_r(\xi) \psi_c^{1/2}}{s_0(2\xi) \psi_b^{1/2}} \delta_{bd} \delta_{\beta\delta}. \quad (3.49)$$

The second term on the right side of (3.46) also vanishes for $\xi \rightarrow \pm i\infty$ so that, assuming $\lambda/\pi \notin \mathbb{Z}$,

$$B^{ra} \left(c \begin{array}{c} d \ \delta \\ b \ \beta \end{array} \middle| u, \pm i\infty \right) = \pm \frac{i e^{\mp i r \lambda} \psi_c^{1/2}}{2 \sin \lambda \psi_b^{1/2}} \delta_{bd} \delta_{\beta\delta}. \quad (3.50)$$

Comparing the right sides of (3.49) or (3.50) with the $(1, a)$ boundary weights (3.31), we see that at $u = 0$ or $\xi \rightarrow \pm i\infty$ the nonzero (r, a) boundary weights reduce, up to unimportant normalization, to $(1, b)$ boundary weights, with each $(1, b)$ weight, for any b , appearing F_{ab}^r (which may be zero) times.

Finally, we note that a gauge transformation of the boundary edge weights,

$$E^{ra}(b, c)_{\beta\gamma} \mapsto \sum_{\beta'=1}^{F_{ba}^r} \sum_{\gamma'=1}^{F_{ca}^{r+1}} S^{ra}(b)_{\beta\beta'} S^{r+1,a}(c)_{\gamma\gamma'} E^{ra}(b, c)_{\beta'\gamma'}, \quad (3.51)$$

induces a gauge transformation (3.35) of the boundary weights, for any $S^{ra}(e)$ satisfying (3.36).

3.7 Transfer Matrices and the Partition Function

We now proceed to a study of some aspects of the complete lattice. We shall be considering a square lattice on a cylinder of width N and circumference $2M$ lattice spacings, with the left boundary condition and boundary field given by (r_1, a_1) and ξ_1 and the right boundary condition and boundary field given by (r_2, a_2) and ξ_2 . In particular, we shall express the partition function for the model using double-row transfer matrices, these being defined in terms of the bulk and boundary weights of the previous sections. Double-row transfer matrices of this type were introduced in [2] and first used for interaction-round-a-face models in [33].

An additional feature of the lattice to be considered here is that alternate rows will be associated with spectral parameter values u and $\lambda - u$. Also, the left boundary will be associated with the spectral parameter value $\lambda - u$ and the right boundary with value u . These values are used since they result in the double-row transfer matrices forming a commuting family. The most physically relevant point is the isotropic point $u = \lambda/2$, at which all rows and both boundaries are associated with the same value of the spectral parameter. Combining this with the conformal point described in the previous section, the case of most interest here is thus $u = \xi_1 = \xi_2 = \lambda/2$.

We begin by defining a set of paths consistent with boundary conditions (r_1, a_1) and (r_2, a_2) and lattice width N ,

$$\mathcal{G}_{r_1 a_1 | r_2 a_2}^N = \left\{ (\beta_1, b_0, \dots, b_N, \beta_2) \mid (b_0, \dots, b_N) \in \mathcal{G}^{N+1}, F_{a_1 b_0}^{r_1} F_{b_N a_2}^{r_2} > 0, \right. \\ \left. \beta_1 \in \{1, \dots, F_{a_1 b_0}^{r_1}\}, \beta_2 \in \{1, \dots, F_{b_N a_2}^{r_2}\} \right\}. \quad (3.52)$$

We see that

$$|\mathcal{G}_{r_1 a_1 | r_2 a_2}^N| = (F^{r_1} G^N F^{r_2})_{a_1 a_2}, \quad (3.53)$$

which is invariant under interchange of a_1 and a_2 or of r_1 and r_2 , since F^{r_1} , F^{r_2} and G are symmetric and mutually commuting matrices.

We now introduce a double-row transfer matrix $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ with rows and columns labeled by the paths of $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ and entries defined by

$$\begin{aligned} \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)_{(\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2)} = \\ \sum_{\substack{(c_0, \dots, c_N) \in \mathcal{G}^{N+1} \\ (\prod_{j=0}^N G_{b_j c_j} G_{c_j d_j} = 1)}} B^{r_1 a_1} \left(\begin{array}{ccc} c_0 & d_0 & \delta_1 \\ & b_0 & \beta_1 \end{array} \middle| \lambda - u, \xi_1 \right) \times \\ \left[\prod_{j=0}^{N-1} W \left(\begin{array}{cc} c_j & c_{j+1} \\ b_j & b_{j+1} \end{array} \middle| u \right) W \left(\begin{array}{cc} d_j & d_{j+1} \\ c_j & c_{j+1} \end{array} \middle| \lambda - u \right) \right] B^{r_2 a_2} \left(\begin{array}{ccc} c_N & d_N & \delta_2 \\ & b_N & \beta_2 \end{array} \middle| u, \xi_2 \right) \end{aligned} \quad (3.54)$$

$$= \begin{array}{c} \delta_1 \quad d_0 \quad d_0 \quad d_1 \quad \quad \quad d_{N-1} \quad d_N \quad d_N \quad \delta_2 \\ \diagdown \quad \diagup \quad \diagdown \quad \diagup \quad \quad \quad \diagdown \quad \diagup \quad \diagdown \quad \diagup \\ \lambda - u, \xi_1 \quad \lambda - u \quad \lambda - u \quad \lambda - u \quad \lambda - u \quad \lambda - u \quad \lambda - u \quad \lambda - u \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \quad \quad \quad \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ u \quad u \quad u \quad u \quad u \quad u \quad u \quad u \\ \beta_1 \quad b_0 \quad b_0 \quad b_1 \quad \quad \quad b_{N-1} \quad b_N \quad b_N \quad \beta_2 \end{array} .$$

We note that if $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ is empty, then $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ is zero-dimensional with its value taken as 0.

$$\mathbf{Z}_{r_1 a_1 | r_2 a_2}^{NM}(u, \xi_1, \xi_2) = \text{tr}(\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2))^M$$

We can see from the first equality of (3.55) that the task of evaluating the partition function is equivalent to that of evaluating the eigenvalues $\Lambda_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)_k$, $k = 1, \dots, (F^{r_1} G^N F^{r_2})_{a_1 a_2}$, of $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$, with

3.8 Transfer Matrix Properties

30

3.8.1 Commutation

It follows from the Yang-Baxter equation (3.12), inversion relation (3.13) and boundary Yang-Baxter equation (3.33) that the double-row transfer matrices commute for any two values, u and v , of the spectral parameter,

$$\left[\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2), \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(v, \xi_1, \xi_2) \right] = 0. \quad (3.57)$$

This can be proved diagrammatically, as done in Section 3.4 of [33].

3.8.2 Transposition

It follows straightforwardly from (3.10) and (3.38) that each double-row transfer matrix is similar to a symmetric matrix. More specifically, defining

$$\mathbf{A}_{r_1 a_1 | r_2 a_2}^N(\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2) = \frac{\psi_{b_N}^{1/4}}{\psi_{b_0}^{1/4}} \delta_{(\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2)} \quad (3.58)$$

and

$$\tilde{\mathbf{D}}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) = \mathbf{A}_{r_1 a_1 | r_2 a_2}^N \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) (\mathbf{A}_{r_1 a_1 | r_2 a_2}^N)^{-1}, \quad (3.59)$$

we have

$$\left(\tilde{\mathbf{D}}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) \right)^T = \tilde{\mathbf{D}}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2). \quad (3.60)$$

This implies that if $\tilde{\mathbf{D}}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ is real, as for example occurs if ψ is the Perron-Frobenius eigenvector and u, ξ_1 and ξ_2 are appropriately chosen, then the eigenvalues of $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ are all real.

3.8.3 Gauge Invariance

We see that the model is invariant under any gauge transformation (3.35) of the boundary weights since this results only in a similarity transformation of the double-row transfer matrix,

$$\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) \mapsto \mathbf{S}_{r_1 a_1 | r_2 a_2}^N \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) (\mathbf{S}_{r_1 a_1 | r_2 a_2}^N)^{-1}, \quad (3.61)$$

where

$$\begin{aligned} \mathbf{S}_{r_1 a_1 | r_2 a_2}^N (\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2) = \\ S^{r_1 a_1}(b_0)_{\beta_1 \delta_1} S^{r_2 a_2}(b_N)_{\beta_2 \delta_2} \delta_{(b_0, \dots, b_N), (d_0, \dots, d_N)}. \end{aligned} \quad (3.62)$$

3.8.4 Simplification at Completely Anisotropic Points

It follows from the anisotropy property (3.11), boundary anisotropy property (3.49), crossing symmetry (3.10) and boundary crossing symmetry (3.39) that at the completely anisotropic points, $u = 0$ and $u = \lambda$, the double-row transfer matrices are proportional to the identity,

$$\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(0, \xi_1, \xi_2) = \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\lambda, \xi_1, \xi_2) = \frac{S_2 s_0(\xi_1) s_0(\xi_2) s_{r_1}(\xi_1) s_{r_2}(\xi_2)}{s_0(2\xi_1) s_0(2\xi_2)} \mathbf{I}. \quad (3.63)$$

3.8.5 Crossing Symmetry

It follows from the Yang-Baxter equation (3.12), inversion relation (3.13) and boundary crossing symmetry (3.39) that the double-row transfer matrices satisfy crossing symmetry,

$$\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\lambda - u, \xi_1, \xi_2) = \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2). \quad (3.64)$$

This, like (3.57), can be proved diagrammatically, as done in Section 3.3 of [33].

3.8.6 Left-Right Symmetry

It follows from reflection symmetry (3.9) and boundary reflection symmetry (3.38) that on interchanging the left and right boundary conditions and boundary fields, we have

$$\mathbf{D}_{r_2 a_2 | r_1 a_1}^N(u, \xi_2, \xi_1) \mathbf{R}_{r_1 a_1 | r_2 a_2}^N = \mathbf{R}_{r_1 a_1 | r_2 a_2}^N \left(\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\lambda - u, \xi_1, \xi_2) \right)^T, \quad (3.65)$$

where $\mathbf{R}_{r_1 a_1 | r_2 a_2}^N$ is a square matrix with rows labeled by the paths of $\mathcal{G}_{r_2 a_2 | r_1 a_1}^N$, columns labeled by the paths of $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ and entries given by

$$\mathbf{R}_{r_1 a_1 | r_2 a_2}^N (\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2) = \delta_{(\beta_2, b_N, \dots, b_0, \beta_1), (\delta_1, d_0, \dots, d_N, \delta_2)}. \quad (3.66)$$

Combining (3.65) and the invertibility of $\mathbf{R}_{r_1 a_1 | r_2 a_2}^N$ with (3.60) and (3.64), we see that $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ and $\mathbf{D}_{r_2 a_2 | r_1 a_1}^N(u, \xi_2, \xi_1)$ are related by a similarity transformation, so that this complete interchanging of the left and right boundaries is a symmetry of the model.

3.8.7 Symmetry under Interchange of r_1, ξ_1 and r_2, ξ_2

It can also be shown that under interchange of r_1, ξ_1 and r_2, ξ_2 , we have

$$\mathbf{D}_{r_2 a_1 | r_1 a_2}^N(u, \xi_2, \xi_1) \mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2) = \mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2) \mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2), \quad (3.67)$$

where $\mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2)$ is a square matrix with rows labeled by the paths of $\mathcal{G}_{r_2 a_1 | r_1 a_2}^N$, columns labeled by the paths of $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ and entries given by

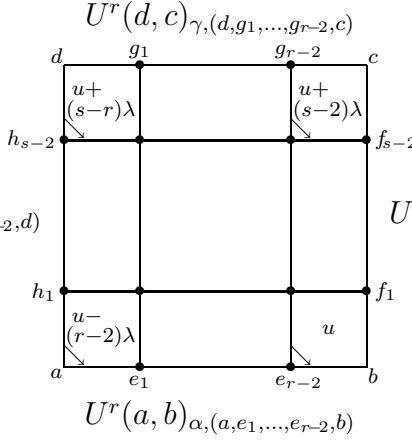
$$\begin{aligned} \mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2)_{(\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2)} &= \frac{\psi_{b_0}^{1/4} \psi_{b_N}^{1/4} \psi_{d_0}^{1/4} \psi_{d_N}^{1/4}}{\psi_{a_1}^{1/2} \psi_{a_2}^{1/2}} \times \\ &\sum_{\substack{(c_0, \dots, c_{N-1}) \in \mathcal{G}^N \\ (G_{c_{N-1} a_2} \prod_{j=0}^{N-1} F_{b_j c_j}^{r_1} F_{c_j d_j}^{r_2} > 0)}} \sum_{\alpha_0=1}^{F_{b_0 c_0}^{r_1}} \dots \sum_{\alpha_{N-1}=1}^{F_{b_{N-1} c_{N-1}}^{r_1}} \sum_{\gamma_0=1}^{F_{c_0 d_0}^{r_2}} \dots \sum_{\gamma_{N-1}=1}^{F_{c_{N-1} d_{N-1}}^{r_2}} W^{r_2 r_1} \left(\begin{array}{ccc} d_0 & \gamma_0 & c_0 \\ \delta_1 & & \alpha_0 \\ a_1 & \beta_1 & b_0 \end{array} \middle| \begin{array}{c} \xi_1 - \xi_2 \\ +\lambda \end{array} \right) \\ &\times \left[\prod_{j=0}^{N-1} W^{2r_1} \left(\begin{array}{ccc} c_j & 1 & c_{j+1} \\ \alpha_j & & \alpha_{j+1} \\ b_j & 1 & b_{j+1} \end{array} \middle| \xi_1 + 2\lambda \right) W^{2r_2} \left(\begin{array}{ccc} d_j & 1 & d_{j+1} \\ \gamma_j & & \gamma_{j+1} \\ c_j & 1 & c_{j+1} \end{array} \middle| \xi_2 + \lambda \right) \right], \end{aligned} \quad (3.68)$$

in which we take $c_N = a_2$, $\alpha_N = \beta_2$ and $\gamma_N = \delta_2$.

The weights which appear in (3.68) are fused bulk weights which are defined, for

each $r, s \in \{1, \dots, g-1\}$, as fused $r-1$ by $s-1$ blocks of bulk weights,

$$W^{rs} \left(\begin{array}{ccc|c} d & \gamma & c & \\ \delta & & \beta & \\ a & \alpha & b & u \end{array} \right) =$$


(3.69)

These fused weights can be regarded as lattice generalizations of the 1 by $r-1$ and $r-1$ by 1 fused blocks considered in (2.20). They satisfy a generalized Yang-Baxter equation, as given in (3.39) of [44], and it is by using this equation, and expressing the boundary weights in the double row transfer matrices in the form (3.32), that (3.67) can be proved. In doing this, it is the $(\xi_1 + 2\lambda)$ -dependent 1 by $r_1 - 1$ fused weights in (3.68) which, together with the generalized Yang-Baxter equation, allow the ξ_1 -dependent $r_1 - 1$ by 2 fused block of bulk weights within the left boundary weight to be propagated to the right. Similarly, it is the $(\xi_2 + \lambda)$ -dependent 1 by $r_2 - 1$ fused weights which allow the ξ_2 -dependent $r_2 - 1$ by 2 fused block within the right boundary weight to be propagated to the left, and it is the $(\xi_1 - \xi_2 + \lambda)$ -dependent $r_2 - 1$ by $r_1 - 1$ fused weight which allows the two blocks of bulk weights from the left and right boundary weights to be interchanged.

We also note that the generalized Yang-Baxter equation allows the fused weights within $\mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2)$ to be rearranged. In particular, the $(\xi_1 - \xi_2 + \lambda)$ -dependent fused weight, which in (3.68) is on the far left of the lattice row, can be propagated to an arbitrary position further to the right, while reversing the order of the $(\xi_1 + 2\lambda)$ - and $(\xi_2 + \lambda)$ -dependent fused weights to the left of its final position. This essentially corresponds to the fact that, in proving (3.67), the order with which the blocks from

the left and right boundaries are interchanged is arbitrary.

By using a generalized inversion relation, it can also be shown that $\mathbf{C}_{r_1 a_1 | r_2 a_2}^N(\xi_1, \xi_2)$ is invertible (except at isolated values of ξ_1 or ξ_2 which, by continuity, are unimportant), its inverse being proportional to $\mathbf{C}_{r_2 a_1 | r_1 a_2}^N(\xi_2, \xi_1)$. It thus follows that transfer matrices with r_1, ξ_1 and r_2, ξ_2 interchanged are related by a similarity transformation, so that this partial interchanging of the left and right boundaries is a symmetry of the model.

Finally, we note that a simple generalization of the results of this section is that it is also possible, up to similarity transformation, to propagate the fused block of bulk weights within either boundary weight to an arbitrary position within the interior of the transfer matrix. The importance of this observation is that it is consistent with the viewpoint in conformal field theory of the boundary conditions corresponding to local operators.

3.8.8 Properties Arising from $\xi \rightarrow i\infty$

Various properties follow from the $\xi \rightarrow i\infty$ (or equivalently $\xi \rightarrow -i\infty$) form (3.50) of the boundary weights.

For example, applying this limit to both the left and right boundary fields we find that $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, i\infty, i\infty)$ is proportional to a direct sum, over $a_1', a_2' \in \mathcal{G}$, of $\mathbf{D}_{1 a_1' | 1 a_2'}^N(u, \xi_1, \xi_2)$, with this term being repeated $F_{a_1 a_1'}^{r_1} F_{a_2 a_2'}^{r_2}$ times in the sum.

As a further example, we can attach an additional $r_1 - 1$ by 2 fused block on the left and an additional $r_2 - 1$ by 2 fused block on the right of $\mathbf{D}_{r_1' a_1' | r_2' a_2'}^N(u, \xi_1, \xi_2)$, where each of these blocks is of the same form as that in (3.32) and we take $\xi \rightarrow i\infty$ in each. We then find, from (3.50), that the resulting matrix is proportional to a corresponding direct sum and, using methods similar to those of Section 3.8.7, that the two attached blocks can be interchanged up to similarity transformation. This therefore gives the result

$$\bigoplus_{a_1', a_2' \in \mathcal{G}} F_{a_1 a_1'}^{r_1} F_{a_2 a_2'}^{r_2} \mathbf{D}_{r_1' a_1' | r_2' a_2'}^N(u, \xi_1, \xi_2) \approx \bigoplus_{a_1', a_2' \in \mathcal{G}} F_{a_1 a_1'}^{r_2} F_{a_2 a_2'}^{r_1} \mathbf{D}_{r_1' a_1' | r_2' a_2'}^N(u, \xi_1, \xi_2), \quad (3.70)$$

where \approx indicates equality up to similarity transformation and the superscripts on

\oplus indicate the number of times that the corresponding terms appear in the direct sum. This relation implies that

$$\sum_{a_1', a_2' \in \mathcal{G}} F_{a_1 a_1'}^{r_1} F_{a_2 a_2'}^{r_2} \mathbf{Z}_{r_1' a_1' | r_2' a_2'}^{NM}(u, \xi_1, \xi_2) = \sum_{a_1', a_2' \in \mathcal{G}} F_{a_1 a_1'}^{r_2} F_{a_2 a_2'}^{r_1} \mathbf{Z}_{r_1' a_1' | r_2' a_2'}^{NM}(u, \xi_1, \xi_2). \quad (3.71)$$

3.8.9 Decomposition into Single-Row Transfer Matrices at the Conformal Point

It follows from (3.47) that if both boundaries are at their conformal point, that is if $u = \lambda - \xi_1 = \xi_2 \equiv \xi$, then the double-row transfer matrix decomposes into a product of two single-row transfer matrices. We denote these, generally not square, matrices as $\check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi)$, with rows labeled by the paths of $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ and columns labeled by the paths of $\mathcal{G}_{r_1+1, a_1 | r_2+1, a_2}^N$, and $\hat{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi)$, with rows labeled by the paths of $\mathcal{G}_{r_1+1, a_1 | r_2+1, a_2}^N$ and columns labeled by the paths of $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$. The entries of these matrices are given by

$$\begin{aligned} \check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi)_{(\beta_1, b_0, \dots, b_N, \beta_2), (\gamma_1, c_0, \dots, c_N, \gamma_2)} = & \begin{cases} E^{r_1 a_1}(b_0, c_0)_{\beta_1 \gamma_1} \prod_{j=0}^{N-1} W \left(\begin{matrix} c_j & c_{j+1} \\ b_j & b_{j+1} \end{matrix} \middle| \xi \right) E^{r_2 a_2}(b_N, c_N)_{\beta_2 \gamma_2}, & \prod_{j=0}^N G_{b_j c_j} = 1 \\ 0, & \prod_{j=0}^N G_{b_j c_j} = 0 \end{cases} \quad (3.72) \\ = & \begin{array}{c} \begin{array}{ccccccc} \gamma_1 & & c_0 & c_1 & & c_{N-1} & c_N & & \gamma_2 \\ \hline & \swarrow & & & & & & \searrow & \\ & r_1, a_1 & & & & & & & r_2, a_2 \\ & \downarrow & & & & & & \downarrow & \\ \beta_1 & b_0 & \dots & b_0 & b_1 & & b_{N-1} & b_N & \dots & b_N & \beta_2 \end{array} \end{array} \end{aligned}$$

and

$$\begin{aligned}
& \hat{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi)_{(\gamma_1, c_0, \dots, c_N, \gamma_2), (\beta_1, b_0, \dots, b_N, \beta_2)} = \\
& \begin{cases} E^{r_1 a_1}(b_0, c_0)_{\beta_1 \gamma_1} \prod_{j=0}^{N-1} W \left(\begin{matrix} b_j & b_{j+1} \\ c_j & c_{j+1} \end{matrix} \middle| \lambda - \xi \right) E^{r_2 a_2}(b_N, c_N)_{\beta_2 \gamma_2}, & \prod_{j=0}^N G_{c_j b_j} = 1 \\ 0, & \prod_{j=0}^N G_{c_j b_j} = 0 \end{cases} \quad (3.73) \\
& = \text{Diagram of a double-row transfer matrix lattice.}
\end{aligned}$$

The diagram shows a rectangular lattice with vertices labeled β_1, β_2 at the top and γ_1, γ_2 at the bottom. The horizontal edges are labeled $c_0, c_1, \dots, c_{N-1}, c_N$ from left to right. The vertical edges are labeled $b_0, b_1, \dots, b_{N-1}, b_N$ from top to bottom. The left vertical edge is labeled r_1, a_1 and the right vertical edge is labeled r_2, a_2 . The internal edges are labeled $\lambda - \xi$. The diagram is enclosed in a box with a double line on the right side.

We now see, using (3.47), that the decomposition of the double-row transfer matrix at the conformal point is

$$\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\xi, \lambda - \xi, \xi) = \check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) \hat{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi). \quad (3.74)$$

We emphasise that the orientations of the boundary edge weights in the two single-row transfer matrices in (3.74) are opposite with respect to a fixed direction along the boundary. Thus, even at the isotropic point $\xi = \lambda/2$, at which adjacent rows of the lattice become indistinguishable in the bulk, the alternating orientations of the boundary edge weights will still distinguish adjacent rows at the boundaries.

We see from (3.10) that $\hat{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) = (\mathbf{A}_{r_1+1, a_1 | r_2+1, a_2}^N)^{-2} (\check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi))^T (\mathbf{A}_{r_1 a_1 | r_2 a_2}^N)^2$, where $\mathbf{A}_{r_1 a_1 | r_2 a_2}^N$ is given by (3.58), and therefore that

$$\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\xi, \lambda - \xi, \xi) = (\mathbf{A}_{r_1 a_1 | r_2 a_2}^N)^{-1} \tilde{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) \left(\tilde{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) \right)^T \mathbf{A}_{r_1 a_1 | r_2 a_2}^N, \quad (3.75)$$

where $\tilde{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) = \mathbf{A}_{r_1 a_1 | r_2 a_2}^N \check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi) (\mathbf{A}_{r_1 a_1 | r_2 a_2}^N)^{-1}$.

This immediately implies that if $\tilde{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\xi)$ is real, then $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\xi, \lambda - \xi, \xi)$ has all nonnegative eigenvalues.

3.8.10 Properties Arising from Graph Bicolorability

We now consider some properties which arise if the graph \mathcal{G} is bicolorable. Although we have not assumed until now that \mathcal{G} is bicolorable, all of the specific A , D and E cases to be considered in the next section have this property.

Bicolorability of \mathcal{G} means that a parity $\pi_a \in \{-1, 1\}$ can be assigned to each node $a \in \mathcal{G}$ so that adjacent nodes always have opposite parity; that is,

$$G_{ab} = 1 \implies \pi_a \pi_b = -1. \quad (3.76)$$

We now note that it follows from (3.18) that each F^r with r even/odd is an odd/even polynomial in G , which leads to a generalization of (3.76) to a selection rule on the fused adjacency matrices,

$$F_{ab}^r > 0 \implies \pi_a \pi_b = (-1)^{r+1}. \quad (3.77)$$

Proceeding to the effect of graph bicolorability on the lattice model, a square lattice can be naturally divided into two interpenetrating sublattices, with the nearest neighbors of each site on one sublattice being sites on the other. Thus, if \mathcal{G} is bicolorable then the condition that the spin states on neighboring lattice sites be adjacent nodes on \mathcal{G} implies that, in each spin assignment, the spin states on one sublattice all have parity 1, while those on the other all have parity -1 .

Using (3.77), there is also a consistency condition between the left and right boundary conditions,

$$\pi_{a_1} \pi_{a_2} = (-1)^{r_1+r_2+N}, \quad (3.78)$$

since otherwise $\mathcal{G}_{r_1 a_1 | r_2 a_2}^N$ is empty and $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2)$ and $\mathbf{Z}_{r_1 a_1 | r_2 a_2}^{NM}(u, \xi_1, \xi_2)$ are zero. If this condition is satisfied, then the sublattices are fixed by the boundary conditions; that is, the sublattice which contains all parity 1, or all parity -1 , spin states is the same for all possible assignments.

Finally, we note that (3.77) also implies that for each boundary edge $(b, c) \in \mathcal{E}^{ra}$, the parities of b and c are respectively opposite to and the same as $\pi_a (-1)^r$, and that therefore any pair of nodes can appear in only one order in a particular set of boundary edges.

4. Critical Unitary A – D – E Models

In this section, we specialize to the critical unitary A – D – E models, for which \mathcal{G} is an A , D or E Dynkin diagram with Coxeter number g and ψ is the Perron-Frobenius eigenvector of the adjacency matrix. In these cases, $\lambda = \pi/g$ and the regime of interest here is $0 < u < \lambda$. This class of models was first identified and studied in [10]. The A and D models are the critical limits of models introduced in [47] and [48] respectively, but the E models do not have off-critical counterparts. We also note that if ψ is instead taken as a submaximal adjacency matrix eigenvector, then the critical nonunitary A – D – E models are obtained.

Fusion of the A models was introduced in [41, 42, 43], while fusion of the D and E models was first studied in [44]. We shall also consider intertwiner relations among these models, these having been studied in detail in [23, 49, 50, 51]. In particular, we shall find that certain symmetries in the fusion and intertwiner properties of these models lead to various additional properties of the boundary conditions, transfer matrices and partition functions.

We shall also study the explicit forms of the boundary weights and boundary edge weights for these models. For the A models, various methods have previously been used to obtain sets of diagonal boundary weights in [4, 32, 33, 34] and sets containing non-diagonal weights in [4, 31, 32, 34, 35], and all of the A boundary weights found here represent certain cases of these previously-known weights. For the D and E models, sets of diagonal boundary weights were found by direct solution of the boundary Yang-Baxter equation in [34], but most of the sets obtained here contain non-diagonal weights and were not previously known.

Finally, we shall consider the connection between the lattice model boundary conditions at the conformal and isotropic points and the conformal boundary conditions of the corresponding unitary minimal theories.

4.1 Graphs and Adjacency Matrices

The A , D and E Dynkin diagrams with Coxeter number g are explicitly given by

$$A_{g-1} = \underset{1}{\bullet} - \underset{2}{\bullet} - \cdots - \underset{g-2}{\bullet} - \underset{g-1}{\bullet}, \quad g = 2, 3, \dots, \quad (4.1)$$

$$D_{\frac{g}{2}+1} = \underset{1}{\bullet} - \underset{2}{\bullet} - \cdots - \underset{\frac{g}{2}-2}{\bullet} - \underset{\frac{g}{2}-1}{\bullet} \begin{array}{l} \nearrow \underset{\frac{g}{2}^-}{\bullet} \\ \searrow \underset{\frac{g}{2}^+}{\bullet} \end{array}, \quad g = 6, 8, \dots, \quad (4.2)$$

$$E_6 = \underset{1}{\bullet} - \underset{2}{\bullet} - \underset{3}{\bullet} - \underset{4}{\bullet} - \underset{5}{\bullet}, \quad \underset{6}{\bullet} \text{ --- } \underset{3}{\bullet}, \quad g = 12, \quad (4.3)$$

$$E_7 = \underset{1}{\bullet} - \underset{2}{\bullet} - \underset{3}{\bullet} - \underset{4}{\bullet} - \underset{5}{\bullet} - \underset{6}{\bullet}, \quad \underset{7}{\bullet} \text{ --- } \underset{4}{\bullet}, \quad g = 18, \quad (4.4)$$

and

$$E_8 = \underset{1}{\bullet} - \underset{2}{\bullet} - \underset{3}{\bullet} - \underset{4}{\bullet} - \underset{5}{\bullet} - \underset{6}{\bullet} - \underset{7}{\bullet}, \quad \underset{8}{\bullet} \text{ --- } \underset{5}{\bullet}, \quad g = 30. \quad (4.5)$$

We note that when referring to the nodes $\frac{g}{2}^-$ and $\frac{g}{2}^+$ of $D_{\frac{g}{2}+1}$, we shall use the convention that if the superscript is not specified then the choice is immaterial. Furthermore, if a numerical value for $\frac{g}{2}^-$ or $\frac{g}{2}^+$ is required in any equation, it is to be taken as $\frac{g}{2}$.

The eigenvalues of the adjacency matrices of these graphs are $2 \cos(k_j \pi / g)$, $j = 1, \dots, |\mathcal{G}|$, where k_j are the Coxeter exponents, as given explicitly by

$$\begin{aligned} A_{g-1}: \quad k_j &= j, \quad j = 1, \dots, g-1 \\ D_{\frac{g}{2}+1}: \quad k_j &= \begin{cases} 2j-1, & j = 1, \dots, \frac{g}{2} \\ \frac{g}{2}, & j = \frac{g}{2} + 1 \end{cases} \\ E_6: \quad (k_1, \dots, k_6) &= (1, 4, 5, 7, 8, 11) \\ E_7: \quad (k_1, \dots, k_7) &= (1, 5, 7, 9, 11, 13, 17) \\ E_8: \quad (k_1, \dots, k_8) &= (1, 7, 11, 13, 17, 19, 23, 29). \end{aligned} \quad (4.6)$$

It can also be shown that for an integer k , and any A - D - E graph with Coxeter number g ,

$$\exists \text{ an adjacency matrix eigenvector with all non-zero entries and associated eigenvalue } 2 \cos(k\pi/g) \iff k \text{ is coprime to } g. \quad (4.7)$$

We note, as already mentioned in Section 3.4.1, that (4.7) implies that, for any A - D - E case, the maximum fusion level and Coxeter number are equal, and that they can thus both be denoted by g .

Throughout the rest of Section 4, we shall restrict our attention to the unitary A - D - E models, which are associated with the Perron-Frobenius eigenvector and thus with the Coxeter exponent $k_1 = 1$. Therefore, from this point on, we shall take

$$\lambda = \pi/g \quad (4.8)$$

and ψ to be the Perron-Frobenius eigenvector, which can be explicitly given by

$$\psi_a = \begin{cases} S_a, & a = 1, \dots, g-1; & A_{g-1} \\ \begin{cases} S_a, & a = 1, \dots, \frac{g}{2} - 1 \\ 1/(2 \sin \lambda), & a = \frac{g}{2} \end{cases}; & D_{\frac{g}{2}+1} \\ \begin{cases} S_a, & a = 1, \dots, l-3 \\ \sin((l-1)\lambda)/\sin(2\lambda), & a = l-2 \\ 2 \cos((l-2)\lambda), & a = l-1 \\ \sin((l-3)\lambda)/\sin(2\lambda), & a = l \end{cases}; & E_l, l = 6, 7, 8, \end{cases} \quad (4.9)$$

where, from (2.4), $S_a = \sin(a\lambda)/\sin\lambda$.

It is also important here to consider a particular involution $a \mapsto \bar{a}$ of the nodes of each graph, this being given by the graph's \mathbb{Z}_2 symmetry transformation for the A , D_{odd} and E_6 cases and by the identity for the D_{even} , E_7 and E_8 cases. More explicitly, we have

$$\bar{a} = \begin{cases} g-a, & a \in A_{g-1} \\ \frac{g}{2}^\mp, & a = \frac{g}{2}^\pm \in D_{\frac{g}{2}+1}, \quad \frac{g}{2}+1 \text{ odd} \\ 6-a, & a \in E_6 \setminus \{6\} \\ a, & \text{otherwise.} \end{cases} \quad (4.10)$$

We see that the eigenvector entries (4.9) are invariant under this involution,

$$\psi_{\bar{a}} = \psi_a. \quad (4.11)$$

We also observe that each A , D and E graph is bicolourable and that we may set the parities as

$$\pi_a = (-1)^a. \quad (4.12)$$

We now consider the A , D and E fused adjacency matrices. A more comprehensive treatment of these can be found in Appendix B of [9].

For A_{g-1} , we have explicitly

$$F_{ab}^r = \begin{cases} 1; & a+b+r \text{ odd, } |a-b| \leq r-1 \text{ and } r+1 \leq a+b \leq 2g-r-1 \\ 0; & \text{otherwise.} \end{cases} \quad (4.13)$$

We note that F_{ab}^r for A_{g-1} , with $r \neq g$, is actually symmetric in all three indices.

For $D_{\frac{g}{2}+1}$, we have explicitly

$$F_{ab}^r = \begin{cases} 2; & a, b \neq \frac{g}{2}, \ a+b+r \text{ odd, } |a-b| \leq \frac{g}{2} - |\frac{g}{2} - r| - 1 \\ & \text{and } a+b - \frac{g}{2} \geq |\frac{g}{2} - r| + 1 \\ 1; & a, b \neq \frac{g}{2}, \ a+b+r \text{ odd, } |a-b| \leq \frac{g}{2} - |\frac{g}{2} - r| - 1 \\ & \text{and } |a+b - \frac{g}{2}| \leq |\frac{g}{2} - r| - 1 \\ 1; & a \neq \frac{g}{2}, \ b = \frac{g}{2}, \ a + \frac{g}{2} + r \text{ odd and } a \geq |\frac{g}{2} - r| + 1 \\ 1; & a = \frac{g}{2}, \ b \neq \frac{g}{2}, \ b + \frac{g}{2} + r \text{ odd and } b \geq |\frac{g}{2} - r| + 1 \\ 1; & a = \frac{g}{2}^\pm, \ b = \frac{g}{2}^\pm \text{ and } r \equiv 1 \pmod{4} \\ 1; & a = \frac{g}{2}^\pm, \ b = \frac{g}{2}^\mp \text{ and } r \equiv 3 \pmod{4} \\ 0; & \text{otherwise.} \end{cases} \quad (4.14)$$

The fused adjacency matrices for E_6 are given explicitly in Section 4.4.6. We shall not give the E_7 and E_8 fused adjacency explicitly, since they can be obtained straightforwardly using a computer from the recursive definition (3.18), but we note that for E_7 each entry is in $\{0, \dots, 4\}$ and that for E_8 each entry is in $\{0, \dots, 6\}$.

We now list some properties which apply to all of the A , D and E fused adjacency matrices. These properties can be proved by decomposing these matrices in terms of their eigenvalues and eigenvectors as given in [9].

For $r = g$ we have

$$F^g = 0. \quad (4.15)$$

Meanwhile, for $r \in \{1, \dots, g-1\}$, F^r form the basis of a commutative matrix algebra, which is a representation of the Verlinde fusion algebra. These $g-1$ matrices are therefore often referred to as Verlinde matrices and denoted V_r .

These matrices can also be used to define related intertwiner matrices I^a , for each $a \in \mathcal{G}$, with rows labeled by $1, \dots, g-1$, columns labeled by the nodes of \mathcal{G} and entries given by

$$I_{rb}^a = F_{ab}^r. \quad (4.16)$$

Each I^a then intertwines the fused adjacency matrices of \mathcal{G} and those of A_{g-1} ,

$$I^a F(\mathcal{G})^r = F(A_{g-1})^r I^a. \quad (4.17)$$

For $\mathcal{G} = A_{g-1}$, this property simply amounts to the commutation of the A_{g-1} fused adjacency matrices, but if \mathcal{G} is a D or E graph it forms the basis of various relationships between \mathcal{G} and the A graph with the same Coxeter number.

Finally, a property of the A , D and E fused adjacency matrices of particular relevance here is that, for $r \in \{1, \dots, g-1\}$,

$$F_{ab}^{g-r} = F_{\bar{a}b}^r = F_{a\bar{b}}^r. \quad (4.18)$$

An important special case of this is $r = 1$, for which

$$F_{ab}^{g-1} = \delta_{a\bar{b}}. \quad (4.19)$$

4.2 Bulk Weights, Fusion Matrices and Fusion Vectors

We now consider the bulk weights, fusion matrices and fusion vectors of the critical unitary A , D and E models.

We see from (3.6) and (4.9) that the A_{g-1} bulk weights are

$$\begin{aligned} W\left(\begin{array}{cc|c} a\pm 1 & a & u \\ a & a\mp 1 & \end{array}\right) &= s_1(-u) \\ W\left(\begin{array}{cc|c} a & a\pm 1 & u \\ a\mp 1 & a & \end{array}\right) &= \frac{(S_{a-1} S_{a+1})^{1/2} s_0(u)}{S_a} \\ W\left(\begin{array}{cc|c} a & a\pm 1 & u \\ a\pm 1 & a & \end{array}\right) &= \frac{s_a(\pm u)}{S_a}. \end{aligned} \quad (4.20)$$

It can also be shown, using (2.15), (3.8) and (4.20) together with certain results on the fusion of A_{g-1} bulk weights from [43], that the A_{g-1} fusion matrices are given explicitly by

$$\begin{aligned} P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)} &= \\ \left(\prod_{m=2}^{\frac{r+a-b-1}{2}} S_m\right) \left(\prod_{m=2}^{\frac{r-a+b-1}{2}} S_m\right) \left(\prod_{m=\frac{a+b-r+1}{2}}^{\frac{a+b+r-1}{2}} S_m\right) \left(\prod_{m=0}^{r-1} \frac{\epsilon_{c_m} \epsilon_{d_m}}{(S_{c_m} S_{d_m})^{1/2}}\right) / \left(\prod_{m=2}^{r-1} S_m\right), \end{aligned} \quad (4.21)$$

where in the fourth product we set $c_0 = d_0 = a$ and $c_{r-1} = d_{r-1} = b$, and where

$$\epsilon_a = \begin{cases} 1, & a \equiv 0 \text{ or } 1 \pmod{4} \\ -1, & a \equiv 2 \text{ or } 3 \pmod{4}. \end{cases} \quad (4.22)$$

In fact, the only properties of the sign factors required here are $\epsilon_a \in \{-1, 1\}$ and $\epsilon_{a-1} \epsilon_{a+1} = -1$, so any of the three other assignments which satisfy these could be used instead.

We can see from (4.21) that, in keeping with (3.20) and (4.13), each nonzero A_{g-1} fusion matrix has rank 1 and that the corresponding fusion vectors, which are thus uniquely defined up to sign, are given, up to this sign, by

$$\begin{aligned} U^r(a, b)_{1, (a, c_1, \dots, c_{r-2}, b)} &= \\ \left[\left(\prod_{m=2}^{\frac{r+a-b-1}{2}} S_m\right) \left(\prod_{m=2}^{\frac{r-a+b-1}{2}} S_m\right) \left(\prod_{m=\frac{a+b-r+1}{2}}^{\frac{a+b+r-1}{2}} S_m\right) / \left(\prod_{m=2}^{r-1} S_m\right) \right]^{1/2} \left(\prod_{m=0}^{r-1} \frac{\epsilon_{c_m}}{S_{c_m}^{1/2}}\right), \end{aligned} \quad (4.23)$$

where in the last product we set $c_0 = a$ and $c_{r-1} = b$.

Proceeding to $D_{\frac{g}{2}+1}$, it is possible to write expressions, similarly explicit to those for A_{g-1} , for the bulk weights and entries of the fusion matrices and fusion vectors,

for a certain natural choice of these vectors. Since each of these expressions involves many different cases, analogous to those of (4.14), we do give them here. However, we note that, as with A_{g-1} , each $D_{\frac{g}{2}+1}$ bulk weight and fusion vector entry can be expressed as a single product of terms.

We also note that each $D_{\frac{g}{2}+1}$ bulk weight and fusion matrix entry can be expressed as a linear combination of A_{g-1} bulk weights and fusion matrix entries, with the coefficients being products of entries of so-called intertwiner cells. These intertwiner cells, whose exact properties are outlined in [23, 49, 50, 51], serve a similar role at the level of the bulk weights to that served at the level of the adjacency matrices by the intertwiner matrices (4.16). While the expressions provided by these intertwiner cells may not be particularly compact when applied to specific cases, they are still useful for deriving certain general properties using known properties of the intertwiner cells and of the A_{g-1} bulk weights and fusion matrices.

With regard to the E graphs, the number of different cases is particularly large so that the numerical values of fusion matrix and fusion vector entries are probably best evaluated using a computer. While this may result in a somewhat unnatural choice of the fusion vectors, this is largely immaterial since the lattice properties of interest are independent of this choice. We also note that, exactly as with $D_{\frac{g}{2}+1}$, each E bulk weight and fusion matrix entry can be expressed as a linear combination of A_{g-1} bulk weights or fusion matrix entries using intertwiner cells and that these expressions can be used to obtain general properties of the E bulk weights, fusion matrices and fusion vectors.

We now consider some properties which apply to all of the A , D and E graphs. We first note, using (4.11), that the bulk weights are invariant under the involution (4.10),

$$W\left(\begin{array}{cc|c} d & c & u \\ a & b & \end{array}\right) = W\left(\begin{array}{cc|c} \bar{d} & \bar{c} & u \\ \bar{a} & \bar{b} & \end{array}\right). \quad (4.24)$$

We also see similarly that for the fusion matrices,

$$P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)} = P^r(\bar{a}, \bar{b})_{(\bar{a}, \bar{c}_1, \dots, \bar{c}_{r-2}, \bar{b}), (\bar{a}, \bar{d}_1, \dots, \bar{d}_{r-2}, \bar{b})}. \quad (4.25)$$

It follows from this that $U^r(a, b)_{\alpha, (a, c_1, \dots, c_{r-2}, b)}$ and $U^r(\bar{a}, \bar{b})_{\alpha, (\bar{a}, \bar{c}_1, \dots, \bar{c}_{r-2}, \bar{b})}$ correspond to two orthonormal decompositions of both $P^r(a, b)$ and $P^r(\bar{a}, \bar{b})$, and therefore that

these fusion vectors are related by a transformation (3.25),

$$U^r(\bar{a}, \bar{b})_{\alpha, (\bar{a}, \bar{c}_1, \dots, \bar{c}_{r-2}, \bar{b})} = \sum_{\alpha'=1}^{F_{ab}^r} R^r(a, b)_{\alpha\alpha'} U^r(a, b)_{\alpha', (a, c_1, \dots, c_{r-2}, b)}. \quad (4.26)$$

Finally, we note that the fusion matrices $P^{g-1}(a, \bar{a})$, which from (4.19) all have rank 1, can be used to generate the fusion matrices of lower fusion level according to

$$\begin{aligned} \sum_{(b, e_1, \dots, e_{g-r-2}, \bar{a}) \in \mathcal{G}_{b\bar{a}}^{g-r}} P^{g-1}(a, \bar{a})_{(a, c_1, \dots, c_{r-2}, b, e_1, \dots, e_{g-r-2}, \bar{a}), (a, d_1, \dots, d_{r-2}, b, e_1, \dots, e_{g-r-2}, \bar{a})} \\ = \frac{\psi_b}{S_r \psi_a} P^r(a, b)_{(a, c_1, \dots, c_{r-2}, b), (a, d_1, \dots, d_{r-2}, b)}. \end{aligned} \quad (4.27)$$

This can be proved by first obtaining the result for the A graphs using (4.21) and then proceeding to the D and E graphs using intertwiner cells.

4.3 Additional Boundary Condition and Transfer Matrix Properties

We now show that in addition to satisfying all of the properties outlined in Section 3.8, including those of Section 3.8.10 arising from bicolorability with parity (4.12), the critical unitary A - D - E models possess further important symmetries associated with the involutions (4.10) and the intertwiner relations (4.16).

4.3.1 Symmetry under $a_1 \mapsto \bar{a}_1$ and $a_2 \mapsto \bar{a}_2$

We first consider the relationship between the (r, a) and (r, \bar{a}) boundary conditions. It follows straightforwardly from (4.18) and (3.41) that the sets of boundary edges for these boundary conditions are related by

$$\mathcal{E}^{r\bar{a}} = \{(\bar{b}, \bar{c}) \mid (b, c) \in \mathcal{E}^{ra}\}. \quad (4.28)$$

Proceeding to the corresponding boundary edge weights and boundary weights, we find, using (4.26), that

$$E^{r\bar{a}}(\bar{b}, \bar{c})_{\beta\gamma} = \sum_{\beta'=1}^{F_{ba}^r} \sum_{\gamma'=1}^{F_{ca}^{r+1}} S^{ra}(b)_{\beta\beta'} S^{r+1,a}(c)_{\gamma\gamma'} E^{ra}(b, c)_{\beta'\gamma'} \quad (4.29)$$

and

$$B^{r\bar{a}}\left(\bar{c} \begin{array}{c} \bar{d} \\ \bar{b} \end{array} \begin{array}{c} \delta \\ \beta \end{array} \middle| u, \xi\right) = \sum_{\beta'=1}^{F_{ba}^r} \sum_{\delta'=1}^{F_{da}^r} S^{ra}(b)_{\beta\beta'} S^{ra}(d)_{\delta\delta'} B^{ra}\left(c \begin{array}{c} d \\ b \end{array} \begin{array}{c} \delta' \\ \beta' \end{array} \middle| u, \xi\right), \quad (4.30)$$

where the orthonormal transformation matrices in (4.26) and those in (4.29) and (4.30) are related by (3.37).

It now follows from (4.24) and (4.30) that $\mathbf{D}_{r_1\bar{a}_1|r_2\bar{a}_2}^N(u, \xi_1, \xi_2)$ and $\mathbf{D}_{r_1a_1|r_2a_2}^N(u, \xi_1, \xi_2)$ are related by a similarity transformation,

$$\mathbf{D}_{r_1\bar{a}_1|r_2\bar{a}_2}^N(u, \xi_1, \xi_2) \mathbf{H}_{r_1a_1|r_2a_2}^N \mathbf{S}_{r_1a_1|r_2a_2}^N = \mathbf{H}_{r_1a_1|r_2a_2}^N \mathbf{S}_{r_1a_1|r_2a_2}^N \mathbf{D}_{r_1a_1|r_2a_2}^N(u, \xi_1, \xi_2), \quad (4.31)$$

where $\mathbf{S}_{r_1a_1|r_2a_2}^N$ is given by (3.62), using the same $S^{ra}(e)$ as in (4.30), and $\mathbf{H}_{r_1a_1|r_2a_2}^N$ is a square matrix with rows labeled by the paths of $\mathcal{G}_{r_1\bar{a}_1|r_2\bar{a}_2}^N$, columns labeled by the paths of $\mathcal{G}_{r_1a_1|r_2a_2}^N$ and entries given by

$$\mathbf{H}_{r_1a_1|r_2a_2}^N (\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2) = \delta_{(\beta_1, \bar{b}_0, \dots, \bar{b}_N, \beta_1), (\delta_1, d_0, \dots, d_N, \delta_2)}. \quad (4.32)$$

4.3.2 Equivalence of (r, a) and $(g-r-1, \bar{a})$ Boundary Conditions at the Conformal Point

We now show that, at the conformal point and for $r \in \{1, \dots, g-2\}$, the (r, a) and $(g-r-1, \bar{a})$ boundary conditions are equivalent. This equivalence takes the form of the boundary edge weights for each of these boundary conditions being the same, except for a gauge transformation and a reversal of the order of the nodes in each boundary pair, neither of which affects any properties of interest. We shall denote such an equivalence of boundary conditions by \leftrightarrow .

In terms of the set of boundary edges (3.41), it follows from (4.18) that, for $r \in \{1, \dots, g-2\}$, the sets \mathcal{E}^{ra} and $\mathcal{E}^{g-r-1, \bar{a}}$ contain the same pairs of nodes but with opposite ordering; that is,

$$\mathcal{E}^{g-r-1, \bar{a}} = \{(c, b) \mid (b, c) \in \mathcal{E}^{ra}\}. \quad (4.33)$$

We also see, from (4.15), that

$$\mathcal{E}^{g-1, a} = \emptyset, \quad (4.34)$$

so that at the conformal point there are no $(g-1, a)$ boundary conditions.

For the boundary edge weights, the equivalence of the (r, a) and $(g-r-1, \bar{a})$ boundary conditions is

$$E^{g-r-1, \bar{a}}(c, b)_{\gamma\beta} = \sum_{\beta'=1}^{F_{ba}^r} \sum_{\gamma'=1}^{F_{ca}^{r+1}} S^{ra}(b)_{\beta\beta'} S^{r+1, a}(c)_{\gamma\gamma'} E^{ra}(b, c)_{\beta'\gamma'}, \quad (4.35)$$

where $S^{ra}(e)$ are orthonormal matrices satisfying (3.36) which are defined by

$$\begin{aligned} S^{ra}(e)_{\alpha\alpha'} &= (S_r \psi_a / \psi_e)^{1/2} \times \\ &\sum_{(e, b_1, \dots, b_{g-r-2}, \bar{a}) \in \mathcal{G}_{e\bar{a}}^{g-r}} \sum_{(e, c_1, \dots, c_{r-2}, a) \in \mathcal{G}_{ea}^r} U^{g-1}(\bar{a}, a)_{1, (\bar{a}, b_{g-r-2}, \dots, b_1, e, c_1, \dots, c_{r-2}, a)} \times \\ &U^{g-r}(e, \bar{a})_{\alpha, (e, b_1, \dots, b_{g-r-2}, \bar{a})} U^r(e, a)_{\alpha', (e, c_1, \dots, c_{r-2}, a)}. \end{aligned} \quad (4.36)$$

We note that $S^{ra}(e)$ also satisfy

$$S^{ra}(e)^T = S^{g-r, \bar{a}}(e). \quad (4.37)$$

These relations, (4.35) and (4.37), and the orthonormality (3.36) can all be proved using the general properties of the fusion matrices and fusion vectors, (3.15), (3.16), (3.21), (3.22) and those which follow from (2.17), together with (4.27).

We now note that, as labels, (r, a) and $(g-r-1, \bar{a})$ are always distinct since for an A_{odd} , D or E graph g is even so that r and $g-r-1$ are different, while for an A_{even} graph g is odd so that a and $\bar{a} = g-a$ are different. Thus, due to the equivalence (4.35), there are at most $(g-2)|\mathcal{G}|/2$ distinct boundary conditions. Furthermore, by examining the sets of boundary edges (3.41) for each A , D and E case, we find that there are no further equivalences between these sets, either direct or through reversing the order of nodes in each edge. We therefore conclude that

$$\text{number of boundary conditions at the conformal point} = (g-2)|\mathcal{G}|/2. \quad (4.38)$$

Due to the consistency condition (3.78), the implementation of a given left and right boundary condition at their conformal points on a lattice of fixed width can be achieved using only two of the four possibilities which arise from the two versions of each boundary condition. If (r_1, a_1) and (r_2, a_2) is one of these possibilities, then

the other is $(g-r_1-1, \bar{a}_1)$ and $(g-r_2-1, \bar{a}_2)$ and the transfer matrices for the two are related by

$$\begin{aligned} D_{g-r_1-1, \bar{a}_1 | g-r_2-1, \bar{a}_2}^N(\xi, \lambda-\xi, \xi) = \\ \mathbf{S}_{r_1+1, a_1 | r_2+1, a_2}^N \hat{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\lambda-\xi) \check{\mathbf{T}}_{r_1 a_1 | r_2 a_2}^N(\lambda-\xi) (\mathbf{S}_{r_1+1, a_1 | r_2+1, a_2}^N)^{-1}, \end{aligned} \quad (4.39)$$

where $\mathbf{S}_{r_1+1, a_1 | r_2+1, a_2}^N$ is given by (3.62) and (4.36). Comparing this with (3.74) we see that the ordering in the products of single row transfer matrices is different in each, which does not affect the nonzero eigenvalues (although unimportant differences in the number of zero eigenvalues will arise due to the different dimensions of the oppositely-ordered products). We thus see that the partition functions are related by

$$\mathbf{Z}_{g-r_1-1, \bar{a}_1 | g-r_2-1, \bar{a}_2}^{NM}(\xi, \lambda-\xi, \xi) = \mathbf{Z}_{r_1 a_1 | r_2 a_2}^{NM}(\lambda-\xi, \xi, \lambda-\xi). \quad (4.40)$$

Finally, we find, using (2.30) in (3.28), that the boundary edge weight relation (4.35) implies the boundary weight relation

$$B^{g-r, \bar{a}} \left(c \begin{array}{c} d \\ b \end{array} \begin{array}{c} \delta \\ \beta \end{array} \middle| u, \xi \right) = \sum_{\beta'=1}^{F_{ba}^r} \sum_{\delta'=1}^{F_{da}^r} S^{ra}(b)_{\beta\beta'} S^{ra}(d)_{\delta\delta'} B^{ra} \left(c \begin{array}{c} d \\ b \end{array} \begin{array}{c} \delta' \\ \beta' \end{array} \middle| u, -\xi \right), \quad (4.41)$$

with $S^{ra}(e)$ again given by (4.36). This then implies that

$$\mathbf{Z}_{r_1 a_1 | r_2 a_2}^{NM}(u, \xi_1, \xi_2) = \mathbf{Z}_{g-r_1, \bar{a}_1 | r_2 a_2}^{NM}(u, -\xi_1, \xi_2) = \mathbf{Z}_{r_1 a_1 | g-r_2, \bar{a}_2}^{NM}(u, \xi_1, -\xi_2). \quad (4.42)$$

This relation taken at $u = \lambda - \xi_1 = \xi_2 = \lambda - \xi$ is consistent with (4.40) through the equivalence, which follows from (3.48), of the (r, a) boundary condition at $u = -\xi$ and the $(r-1, a)$ boundary condition at $u = \xi$.

4.3.3 Intertwiner Symmetry

We now consider the relationship between the double-row transfer matrices and partition functions of the model based on \mathcal{G} , with Coxeter number g , and those of the model based on A_{g-1} . In particular, we shall find that any critical unitary A – D – E partition function can be expressed as a sum of certain A partition functions.

It can be shown using intertwiner cells that, for each $r_1, r_2, s' \in \{1, \dots, g-1\}$ and $a_1, a_2 \in \mathcal{G}$, we have

$$\begin{aligned} \bigoplus_{a \in \mathcal{G}}^{F_{a_1 a}^{s'}} \mathbf{D}_{r_1 a | r_2 a_2}^N(u, \xi_1, \xi_2) &\approx \bigoplus_{s=1}^{g-1}^{F_{a_1 a_2}^s} \mathbf{D}_{r_1 s' | r_2 s}^{N, A_{g-1}}(u, \xi_1, \xi_2) \\ \bigoplus_{a \in \mathcal{G}}^{F_{a_2 a}^{s'}} \mathbf{D}_{r_1 a_1 | r_2 a}^N(u, \xi_1, \xi_2) &\approx \bigoplus_{s=1}^{g-1}^{F_{a_1 a_2}^s} \mathbf{D}_{r_1 s | r_2 s'}^{N, A_{g-1}}(u, \xi_1, \xi_2), \end{aligned} \quad (4.43)$$

where we are using \approx and the superscripts on \bigoplus in the same ways as in (3.70), and where the fused adjacency matrices on both sides and the transfer matrices on the left sides refer to \mathcal{G} , while the transfer matrices on the right sides refer, as indicated, to A_{g-1} .

Since the two forms of this relation can be proved similarly, and are related through the symmetries of Sections 3.8.6 and 3.8.7, we shall consider, from now on, only the first form.

We first discuss the details of the proof. The similarity transformation in the first line of (4.43) can be implemented by an invertible matrix $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ which pre-multiplies the left side and postmultiplies the right side. The rows of $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ and the rows and columns of $\bigoplus_{s=1}^{g-1} F_{a_1 a_2}^s \mathbf{D}_{r_1 s' | r_2 s}^{N, A_{g-1}}(u, \xi_1, \xi_2)$ are labeled by the paths of

$$\left\{ (t_0, \dots, t_N, t, \alpha_2) \mid (1, t_0, \dots, t_N, 1) \in (A_{g-1})_{r_1 s' | r_2 t}^N, F_{a_1 a_2}^t > 0, \alpha_2 \in \{1, \dots, F_{a_1 a_2}^t\} \right\},$$

while the columns of $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ and the rows and columns of $\bigoplus_{a \in \mathcal{G}}^{F_{a_1 a}^{s'}} \mathbf{D}_{r_1 a | r_2 a_2}^N(u, \xi_1, \xi_2)$ are labeled by the paths of

$$\left\{ (\alpha_1, b, \beta_1, b_0, \dots, b_N, \beta_2) \mid (\beta_1, b_0, \dots, b_N, \beta_2) \in \mathcal{G}_{r_1 b | r_2 a_2}^N, F_{a_1 b}^{s'} > 0, \alpha_1 \in \{1, \dots, F_{a_1 b}^{s'}\} \right\}.$$

The entries of these matrices are given by

$$\begin{aligned} \mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N} (t_0, \dots, t_N, t, \alpha_2), (\alpha_1, b, \beta_1, b_0, \dots, b_N, \beta_2) &= \\ \sum_{\gamma_0=1}^{F_{a_1 b_0}^{t_0}} \dots \sum_{\gamma_N=1}^{F_{a_1 b_N}^{t_N}} Q^{r_1 a_1} \begin{pmatrix} b & \beta_1 & b_0 \\ \alpha_1 & \gamma_0 & \\ s' & 1 & t_0 \end{pmatrix} \left[\prod_{j=0}^{N-1} Q^{a_1} \begin{pmatrix} b_j & b_{j+1} \\ \gamma_j & \gamma_{j+1} \\ t_j & t_{j+1} \end{pmatrix} \right] Q^{r_2 a_1} \begin{pmatrix} b_N & \beta_2 & a_2 \\ \gamma_N & \alpha_2 & \\ t_N & 1 & t \end{pmatrix}, \end{aligned} \quad (4.44)$$

$$\left[\bigoplus_{a \in \mathcal{G}} F_{a_1 a}^{s'} \mathbf{D}_{r_1 a | r_2 a_2}^N(u, \xi_1, \xi_2) \right]_{(\alpha_1, b, \beta_1, b_0, \dots, b_N, \beta_2), (\alpha'_1, d, \delta_1, d_0, \dots, d_N, \delta_2)} =$$

$$\delta_{\alpha_1 \alpha'_1} \delta_{bd} \mathbf{D}_{r_1 b | r_2 a_2}^N(u, \xi_1, \xi_2)_{(\beta_1, b_0, \dots, b_N, \beta_2), (\delta_1, d_0, \dots, d_N, \delta_2)} \quad (4.45)$$

and similarly for $\bigoplus_{s=1}^{g-1} F_{a_1 a_2}^s \mathbf{D}_{r_1 s' | r_2 s}^{N, A_{g-1}}(u, \xi_1, \xi_2)$. In (4.44), Q^{a_1} are intertwiner cells associated with the intertwiner matrix I^{a_1} of (4.16), and $Q^{r_1 a_1}$ and $Q^{r_2 a_1}$ are fused blocks of such cells, of widths $r_1 - 1$ and $r_2 - 1$ respectively. Thus, $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ can be viewed as a row of intertwiner cells in which the spins on the lower left and upper right corners are fixed to s' and a_2 respectively, the lower row of spins between s' and a_2 on A_{g-1} label the rows of the matrix and the upper row of spins between s' and a_2 on \mathcal{G} label the columns of the matrix. We also see that all of the matrices here are square with dimension $(I^{a_1} F^{r_1} G^N F^{r_2})_{s' a_2}$, it being possible using (4.17) to propagate I^{a_1} to the right of this expression while replacing the adjacency matrices of \mathcal{G} with those of A_{g-1} . The intertwiner cells are assumed to satisfy an intertwiner relation, as given in (4.6a) of [49], as well as two inversion relations, as given in (4.6b) and (4.6c) of [49]. It follows immediately from the inversion relations that $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ is invertible, with its inverse being given, up to gauge transformations on the intertwiner cells, by its transpose. Meanwhile, the equation corresponding to the first line of (4.43) can be obtained by using one of the inversion relations to insert a pair of cells between $\mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ and $\bigoplus_{a \in \mathcal{G}} F_{a_1 a}^{s'} \mathbf{D}_{r_1 a | r_2 a_2}^N(u, \xi_1, \xi_2)$, using the intertwiner relation and the form (3.32) of the boundary weights to propagate these cells around a single loop, and then using an inversion relation again to remove the inserted cells, thus giving $\bigoplus_{s=1}^{g-1} F_{a_1 a_2}^s \mathbf{D}_{r_1 s' | r_2 s}^{N, A_{g-1}}(u, \xi_1, \xi_2) \mathbf{J}_{r_1 a_1 | r_2 a_2}^{s' N}$ and completing the proof. We note that this last process is probably best understood diagrammatically, with the lower part of the loop involving the conversion in the lower row of the transfer matrix from \mathcal{G} weights to A_{g-1} weights and the propagation of the row of intertwiner cells to a position between the rows of the transfer matrix, and the upper part of the loop involving the conversion of weights in the upper row of the transfer matrix and the propagation of the row of cells to its final position.

We note that (4.43) is still nontrivial for $\mathcal{G} = A_{g-1}$ and that it then corresponds

to certain cases of (3.70). In fact, the A_{g-1} intertwiner cells Q^a can be obtained by taking a $u \rightarrow i\infty$ limit on fused $a-1$ by 1 blocks of A_{g-1} bulk weights.

We also note that the intertwiner cells Q^a for \mathcal{G} a D or E graph have only been found explicitly, in [23, 49, 50, 51], for $a = 1$. However, for various reasons, the existence of these cells for other values of a seems guaranteed.

Finally, we observe that a particularly important case of (4.43) is $s' = 1$, for which

$$D_{r_1 a_1 | r_2 a_2}^N(u, \xi_1, \xi_2) \approx \bigoplus_{s=1}^{g-1} F_{a_1 a_2}^s D_{r_1 1 | r_2 s}^{N, A_{g-1}}(u, \xi_1, \xi_2), \quad (4.46)$$

which in turn implies that

$$Z_{r_1 a_1 | r_2 a_2}^{NM}(u, \xi_1, \xi_2) = \sum_{s=1}^{g-1} F_{a_1 a_2}^s Z_{r_1 1 | r_2 s}^{NM, A_{g-1}}(u, \xi_1, \xi_2). \quad (4.47)$$

We thus see that the task of evaluating the partition functions of all of the A – D – E models with boundary conditions (r_1, a_1) and (r_2, a_2) has been reduced to that of evaluating the partition functions of just the A models with boundary conditions $(r_1, 1)$ and (r_2, s) .

4.4 Boundary Weights

We now consider the explicit forms of the boundary weights and boundary edge weights for the critical unitary A – D – E models.

4.4.1 A Graphs

For A_{g-1} , we find, using (4.23) in (3.42) and then applying a simple gauge transformation to remove a factor ϵ_c which arises, that the boundary edge weights are given explicitly by

$$E^{ra}(c \pm 1, c)_{11} = \frac{(S_{(r \mp c + a)/2} S_{(c \pm a \mp r)/2})^{1/2}}{(S_{c \pm 1} S_c)^{1/4}}. \quad (4.48)$$

We see that each of these weights is positive. We also see that, for these weights, the relations (4.29) and (4.35) are

$$E^{r, g-a}(g-b, g-c)_{11} = E^{ra}(b, c)_{11}, \quad E^{g-r-1, g-a}(c, b)_{11} = E^{ra}(b, c)_{11}. \quad (4.49)$$

Substituting (4.48) into (3.46) we now find that the A_{g-1} boundary weights are

$$B^{ra} \left(c \begin{array}{cc} c \pm 1 & 1 \\ c \pm 1 & 1 \end{array} \middle| u, \xi \right) = \frac{S_{(r \mp c + a)/2} S_{(c \pm a \mp r)/2} s_0(\xi + u) s_r(\xi - u) + S_{(r \pm c + a)/2} S_{(c \mp a \pm r)/2} s_0(\xi - u) s_r(\xi + u)}{S_r (S_c S_{c \pm 1})^{1/2} s_0(2\xi)} \quad (4.50)$$

$$B^{ra} \left(c \begin{array}{cc} c \mp 1 & 1 \\ c \pm 1 & 1 \end{array} \middle| u, \xi \right) = \frac{(S_{(r-c+a)/2} S_{(r+c-a)/2} S_{(c+a-r)/2} S_{(c+a+r)/2})^{1/2} s_0(2u)}{(S_{c-1} S_{c+1})^{1/4} S_c^{1/2} s_0(2\xi)}.$$

All of the boundary weights which were found as solutions of the boundary Yang-Baxter equation for the A_{g-1} models and their off-critical extensions in [4, 31, 32, 33, 34, 35] can be related to those of (4.50) by using appropriate values for the various parameters involved. In particular, we note that more general boundary weights which depend on two boundary field parameters are known, as for example given in (3.14–3.15) of [4], and that these reduce to the weights (4.50) when one of these parameters is set to $i\infty$.

Some important special cases here are the $(r, 1)$ and $(g-r-1, g-1)$ boundary conditions for which

$$\begin{aligned} \mathcal{E}^{r1} &= \{(r, r+1)\}, & \mathcal{E}^{g-r-1, g-1} &= \{(r+1, r)\}, \\ E^{r1}(r, r+1) &= E^{g-r-1, g-1}(r+1, r) = (S_r S_{r+1})^{1/4}. \end{aligned} \quad (4.51)$$

The corresponding boundary weights are all diagonal and given by

$$B^{r1} \left(r \pm 1 \begin{array}{cc} r & 1 \\ r & 1 \end{array} \middle| u, \xi \right) = B^{g-r, g-1} \left(r \pm 1 \begin{array}{cc} r & 1 \\ r & 1 \end{array} \middle| u, -\xi \right) = \frac{S_{r \pm 1}^{1/2} s_0(\xi \pm u) s_r(\xi \mp u)}{S_r^{1/2} s_0(2\xi)}, \quad (4.52)$$

these weights matching those found in [33]. We see that for $r \in \{2, \dots, g-2\}$ these cases provide an example in which boundary weights which are nonzero away from the conformal point vanish at the conformal point. More specifically, away from the conformal point, these cases represent semi-fixed boundary conditions in which the state of every alternate boundary spin is fixed to be r and that of each spin between these can be $r-1$ or $r+1$, while at the conformal point they represent completely fixed boundary conditions in which only a single boundary spin configuration $\dots r, r+1, r, r+1 \dots$ contributes to the partition function.

Other important cases here are the $(1, a) \leftrightarrow (g-2, g-a)$ boundary conditions, with $a \in \{2, \dots, g-2\}$, for which

$$\begin{aligned}\mathcal{E}^{1a} &= \{(a, a-1), (a, a+1)\}, \quad \mathcal{E}^{g-2, g-a} = \{(a-1, a), (a+1, a)\}, \\ E^{1a}(a, a \pm 1) &= E^{g-2, g-a}(a \pm 1, a) = (S_{a \pm 1}/S_a)^{1/4}.\end{aligned}\tag{4.53}$$

As already seen for the general case in (3.31), these are semi-fixed boundary conditions in which the state of every alternate boundary spin is fixed to be a .

We now observe that the only cases in which every edge of A_{g-1} appears, in one order, in the set of boundary edges are

$$\begin{aligned}g \text{ odd: } &\begin{cases} \mathcal{E}^{\frac{g-1}{2}, \frac{g-1}{2}} = \{(1, 2), (3, 2), \dots, (g-2, g-3), (g-2, g-1)\} \\ \mathcal{E}^{\frac{g-1}{2}, \frac{g+1}{2}} = \{(2, 1), (2, 3), \dots, (g-3, g-2), (g-1, g-2)\} \end{cases} \\ g \text{ even: } &\begin{cases} \mathcal{E}^{\frac{g}{2}-1, \frac{g}{2}} = \{(2, 1), (2, 3), \dots, (g-2, g-3), (g-2, g-1)\} \\ \mathcal{E}^{\frac{g}{2}, \frac{g}{2}} = \{(1, 2), (3, 2), \dots, (g-3, g-2), (g-1, g-2)\}. \end{cases}\end{aligned}\tag{4.54}$$

These cases therefore represent boundary conditions in which each configuration of boundary spins consistent with fixed even-spin and odd-spin sublattices contributes a nonzero weight to the partition function at the conformal point. If these weights are all equal, which in fact only occurs for A_3 , we refer to the boundary condition as free, while if the weights are not all equal we refer to it as quasi-free.

Finally, we note that all other boundary conditions not of the fixed, semi-fixed, quasi-free or free type can be regarded as intermediate between these types.

4.4.2 Example: A_3

We now consider, as an example, the case A_3 , this being the simplest nontrivial A model. For any spin assignment in the A_3 model, the spin states on one sublattice are all 2, while each spin state on the other is either 1 or 3. The former sublattice, being frozen in a single configuration, can therefore be discarded and the model viewed as a two-state model on the other sublattice. It can be shown that the bulk weights of this model are those of the critical Ising model, with the horizontal and vertical coupling constants suitably parameterized in terms of the spectral parameter. It is

therefore natural to relabel the nodes of A_3 as a frozen state 0 and Ising states $+$ and $-$; that is,

$$A_3 = \begin{array}{c} \bullet \text{---} \bullet \text{---} \bullet \\ + \quad 0 \quad - \end{array} . \quad (4.55)$$

The A_3 fused adjacency matrices are, from (4.13),

$$F^1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad F^2 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad F^3 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad F^4 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}. \quad (4.56)$$

Using these matrices to determine each set of boundary edges and then (4.48) to give the corresponding weights, we find that these weights are, up to normalization, as given in Table 1.

$-$	$E(-,0)_{11} = 1$	$E(0,+)_{11} = 1$
0	$E(0,+)_{11} = E(0,-)_{11} = 1$	$E(+,0)_{11} = E(-,0)_{11} = 1$
$+$	$E(+,0)_{11} = 1$	$E(0,-)_{11} = 1$
$\begin{array}{c} a \\ r \end{array}$	1	2

Table 1: A_3 boundary edge weights

We see that the three A_3 boundary conditions at the conformal point are:

- $(1, +) \leftrightarrow (2, -) \leftrightarrow +$ fixed
- $(1, -) \leftrightarrow (2, +) \leftrightarrow -$ fixed
- $(1, 0) \leftrightarrow (2, 0) \leftrightarrow$ free.

We note that the last of these boundary conditions is invariant under the model's \mathbb{Z}_2 symmetry, while the first two are not.

4.4.3 Example: A_4

We now consider, as another example, the case A_4 . It is known that this model can related to the tricritical hard square and tricritical Ising models.

The A_4 fused adjacency matrices are

$$\begin{aligned}
F^1 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} & F^2 &= \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} & F^3 &= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \\
F^4 &= \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} & F^5 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.
\end{aligned} \tag{4.57}$$

Using these and (4.48), we find that the A_4 boundary edge weights are, up to normalization, as given in Table 2.

4	$E(4,3)_{11} = 1$	$E(3,2)_{11} = 1$	$E(2,1)_{11} = 1$
3	$E(3,2)_{11} = (\sqrt{5}+1)^{1/8}$ $E(3,4)_{11} = (\sqrt{5}-1)^{1/8}$	$E(2,1)_{11} = E(4,3)_{11}$ $= (\sqrt{5}+1)^{1/8}$ $E(2,3)_{11} = (5\sqrt{5}-11)^{1/8}$	$E(1,2)_{11} = (\sqrt{5}-1)^{1/8}$ $E(3,2)_{11} = (\sqrt{5}+1)^{1/8}$
2	$E(2,1)_{11} = (\sqrt{5}-1)^{1/8}$ $E(2,3)_{11} = (\sqrt{5}+1)^{1/8}$	$E(1,2)_{11} = E(3,4)_{11}$ $= (\sqrt{5}+1)^{1/8}$ $E(3,2)_{11} = (5\sqrt{5}-11)^{1/8}$	$E(2,3)_{11} = (\sqrt{5}+1)^{1/8}$ $E(4,3)_{11} = (\sqrt{5}-1)^{1/8}$
1	$E(1,2)_{11} = 1$	$E(2,3)_{11} = 1$	$E(3,4)_{11} = 1$
$\frac{a}{r}$	1	2	3

Table 2: A_4 boundary edge weights

We see that the six A_4 boundary conditions at the conformal point are:

- $(1, 1) \leftrightarrow (3, 4) \leftrightarrow \dots 1, 2, 1, 2 \dots$ fixed
- $(1, 4) \leftrightarrow (3, 1) \leftrightarrow \dots 3, 4, 3, 4 \dots$ fixed
- $(2, 1) \leftrightarrow (2, 4) \leftrightarrow \dots 2, 3, 2, 3 \dots$ fixed
- $(1, 2) \leftrightarrow (3, 3) \leftrightarrow \dots 2, 1/3, 2, 1/3 \dots$ semi-fixed
- $(1, 3) \leftrightarrow (3, 2) \leftrightarrow \dots 3, 2/4, 3, 2/4 \dots$ semi-fixed
- $(2, 2) \leftrightarrow (2, 3) \leftrightarrow$ quasi-free.

4.4.4 D Graphs

For $D_{\frac{g}{2}+1}$, we find, by substituting the fusion vector entries described in Section 4.2 into (3.42) and then applying certain simple gauge transformations, that the boundary edge weights can be taken explicitly as

$$\begin{aligned}
E^{ra}(b, c)_{11} &= \begin{cases} 2^{-1/4} |_{b, c = \frac{g}{2}} E_A^{ra}(b, c)_{11} ; & a \neq \frac{g}{2}, \quad r \leq \frac{g}{2} - 1 \\ 2^{-1/4} |_{b, c = \frac{g}{2}} E_A^{r, g-a}(b, c)_{11} ; & a \neq \frac{g}{2}, \quad r \geq \frac{g}{2} \\ 2^{1/4} |_{b, c = \frac{g}{2}} E_A^{r, \frac{g}{2}}(b, c)_{11} ; & a = \frac{g}{2} \end{cases} \\
E^{ra}(b, c)_{12} &= \begin{cases} 0 ; & b \neq \frac{g}{2} \\ \pm 2^{-1/4} E_A^{r, g-a}(\frac{g}{2}, \frac{g}{2} - 1)_{11} ; & b = \frac{g}{2}^\pm, \quad r \leq \frac{g}{2} - 1 \\ \pm 2^{-1/4} E_A^{ra}(\frac{g}{2}, \frac{g}{2} - 1)_{11} ; & b = \frac{g}{2}^\pm, \quad r \geq \frac{g}{2} \end{cases} \quad (4.58) \\
E^{ra}(b, c)_{21} &= \begin{cases} 0 ; & c \neq \frac{g}{2} \\ \pm 2^{-1/4} E_A^{r, g-a}(\frac{g}{2} - 1, \frac{g}{2})_{11} ; & c = \frac{g}{2}^\pm, \quad r \leq \frac{g}{2} - 1 \\ \pm 2^{-1/4} E_A^{ra}(\frac{g}{2} - 1, \frac{g}{2})_{11} ; & c = \frac{g}{2}^\pm, \quad r \geq \frac{g}{2} \end{cases} \\
E^{ra}(b, c)_{22} &= \begin{cases} E_A^{r, g-a}(b, c)_{11} ; & r \leq \frac{g}{2} - 1 \\ E_A^{ra}(b, c)_{11} ; & r \geq \frac{g}{2}, \end{cases}
\end{aligned}$$

where by $X|_{b, c = \frac{g}{2}}$ we mean that X is only to be included if $b = \frac{g}{2}$ or $c = \frac{g}{2}$, and where $E_A^{ra}(b, c)_{11}$ are the A_{g-1} boundary edge weights as given by (4.48). The fact that the $D_{\frac{g}{2}+1}$ boundary edge weights can be expressed in terms of A_{g-1} boundary edge weights follows from the intertwiner relations between the corresponding models.

We see that for any boundary condition, and in this gauge, there is at most one negative boundary edge weight. We also see that, for these weights, the relations (4.29) and (4.35) are

$$E^{r\bar{a}}(\bar{b}, \bar{c})_{\beta\gamma} = \sigma_{\beta\gamma} E^{ra}(b, c)_{\beta\gamma}, \quad E^{g-r-1, \bar{a}}(c, b)_{\gamma\beta} = E^{ra}(b, c)_{\beta\gamma}, \quad (4.59)$$

where

$$\sigma_{\beta\gamma} = \begin{cases} -1, & D_{\text{odd}} \text{ with } \beta \neq \gamma \\ 1, & \text{otherwise.} \end{cases} \quad (4.60)$$

In fact, for D_{even} the first relation of (4.59) is trivial since the involution $a \mapsto \bar{a}$ is the identity, but we note that the relation still holds if the involution is instead taken to be the graph's \mathbb{Z}_2 symmetry transformation and if $\sigma_{12} = \sigma_{21}$ are replaced by -1 .

Boundary weights for $D_{\frac{g}{2}+1}$ can be obtained by substituting the edge weights (4.58) into (3.46). For some of the boundary conditions, all of the boundary weights are diagonal and these weights can be related to those previously found in [34]. However, non-diagonal boundary weights for the $D_{\frac{g}{2}+1}$ models, apart from one case of D_4 considered in [7], were not previously known. We also note that since some simple, but (r, a) -dependent, gauge transformations have been included in the boundary edge weights of (4.58), some corresponding gauge factors need to be included in equations which relate boundary weights at different values of (r, a) , in particular (3.48) and (4.41).

Finally, we note that, as with A_{g-1} , certain of the $D_{\frac{g}{2}+1}$ boundary conditions can be identified as being of fixed, semi-fixed, free or quasi-free type.

4.4.5 Example: D_4

We now consider, as an example, the case D_4 . For any spin assignment in the D_4 model, the spin states on one sublattice are all 2, while each spin state on the other is 1, 3 or 4, so that the model can be regarded as a three-state model on the latter sublattice. The bulk weights of this model can be shown to be those of the critical three-state Potts model. These bulk weights are also invariant under any \mathcal{S}_3 permutation of the Potts spin states. We shall use the more natural labeling of the nodes of D_4 , $1 \mapsto A$, $2 \mapsto 0$, $3^+ \mapsto B$ and $3^- \mapsto C$; that is,

$$D_4 = \begin{array}{c} \bullet \\ \diagup \\ \bullet \text{---} \bullet \text{---} \bullet \\ \diagdown \\ \bullet \end{array} \begin{array}{c} C \\ \\ A \\ B \end{array} \quad (4.61)$$

The D_4 fused adjacency matrices are, from (4.14),

$$\begin{aligned}
F^1 = F^5 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} & F^2 = F^4 &= \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \\
F^3 &= \begin{pmatrix} 0 & 0 & 1 & 1 \\ 0 & 2 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{pmatrix} & F^5 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix},
\end{aligned} \tag{4.62}$$

where the rows and columns are ordered $A, 0, B, C$. Using these and (4.58), we find that the D_4 boundary edge weights are, up to normalization and a simple gauge transformation on the $(2, 0)$ and $(3, 0)$ boundary conditions which makes their \mathfrak{S}_3 symmetry properties more apparent, as given in Table 3.

C	$E(C,0)_{11} = 1$	$E(0,A)_{11} =$ $E(0,B)_{11} = 1$	$E(A,0)_{11} =$ $E(B,0)_{11} = 1$	$E(0,C)_{11} = 1$
B	$E(B,0)_{11} = 1$	$E(0,A)_{11} =$ $E(0,C)_{11} = 1$	$E(A,0)_{11} =$ $E(C,0)_{11} = 1$	$E(0,B)_{11} = 1$
0	$E(0,A)_{11} =$ $E(0,B)_{11} =$ $E(0,C)_{11} = 1$	$E(A,0)_{11} = 1$ $E(A,0)_{12} = 0$ $E(B,0)_{11} = -1/2$ $E(B,0)_{12} = \sqrt{3}/2$ $E(C,0)_{11} = -1/2$ $E(C,0)_{12} = -\sqrt{3}/2$	$E(0,A)_{11} = 1$ $E(0,A)_{21} = 0$ $E(0,B)_{11} = -1/2$ $E(0,B)_{21} = \sqrt{3}/2$ $E(0,C)_{11} = -1/2$ $E(0,C)_{21} = -\sqrt{3}/2$	$E(A,0)_{11} =$ $E(B,0)_{11} =$ $E(C,0)_{11} = 1$
A	$E(A,0)_{11} = 1$	$E(0,B)_{11} =$ $E(0,C)_{11} = 1$	$E(B,0)_{11} =$ $E(C,0)_{11} = 1$	$E(0,A)_{11} = 1$
$\begin{smallmatrix} a \\ r \end{smallmatrix}$	1	2	3	4

Table 3: D_4 boundary edge weights

We see that the eight D_4 boundary conditions at the conformal point are:

- $(1, A) \leftrightarrow (4, A) \leftrightarrow A$ fixed
- $(1, B) \leftrightarrow (4, B) \leftrightarrow B$ fixed
- $(1, C) \leftrightarrow (4, C) \leftrightarrow C$ fixed
- $(2, A) \leftrightarrow (3, A) \leftrightarrow B$ and C mixed with equal weight
- $(2, B) \leftrightarrow (3, B) \leftrightarrow A$ and C mixed with equal weight
- $(2, C) \leftrightarrow (3, C) \leftrightarrow A$ and B mixed with equal weight
- $(1, 0) \leftrightarrow (4, 0) \leftrightarrow$ free
- $(2, 0) \leftrightarrow (3, 0) \leftrightarrow$ quasi-free in which same-spin pairs have weight 1
and different-spin pairs have weight $-1/2$

The nature of the last boundary condition is best seen by considering the $(2, 0)$ boundary weights at the conformal point, these being, up to normalization,

$$B^{2,0} \left(0 \begin{array}{cc} d & 1 \\ b & 1 \end{array} \middle| \xi, \xi \right) = \begin{cases} 1; & b = d \\ -1/2; & b \neq d, \end{cases} \quad b, d \in \{A, B, C\}. \quad (4.63)$$

This is therefore a boundary condition on nearest-neighbor pairs of Potts spins, in which like and unlike neighbors are associated with weights 1 and $-1/2$ respectively.

We see that the last two D_4 boundary conditions are \mathcal{S}_3 symmetric, while the first six are not. In fact, the $(2, 0)$ boundary weights (4.63) represent the only possibility, other than reproducing the $(1, 0) \leftrightarrow (4, 0)$ weights, which is \mathcal{S}_3 symmetric and consistent with a decomposition (3.47) in which γ is summed over two values.

4.4.6 E Graphs

For the E graphs, there are a large number of boundary conditions at the conformal point (specifically, 30 for E_6 , 56 for E_7 and 112 for E_8) and many of these are in turn associated with a large number of boundary edge weights. Therefore, since it is straightforward and more practical to obtain the numerical values for these weights using a computer, we do not list them here. However, as an example, we do give the sets of E_6 boundary edges.

The E_6 fused adjacency matrices are

$$\begin{aligned}
F^1 &= \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} & F^2 &= \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \end{pmatrix} & F^3 &= \begin{pmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \end{pmatrix} \\
F^4 &= \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 2 & 0 & 1 & 0 \\ 0 & 2 & 0 & 2 & 0 & 1 \\ 1 & 0 & 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 \end{pmatrix} & F^5 &= \begin{pmatrix} 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 2 & 0 & 1 \\ 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 2 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \end{pmatrix} & F^6 &= \begin{pmatrix} 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 2 & 0 & 2 & 0 & 2 \\ 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \end{pmatrix} \\
F^7 &= \begin{pmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 1 & 0 & 1 \\ 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 0 & 2 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \end{pmatrix} & F^8 &= \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 2 & 0 & 1 \\ 0 & 0 & 2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 \end{pmatrix} & F^9 &= \begin{pmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \end{pmatrix} \\
F^{10} &= \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \end{pmatrix} & F^{11} &= \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} & F^{12} &= \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.
\end{aligned} \tag{4.64}$$

Using these, we find that the E_6 boundary edges are as given in Table 4. In this table we also give, for each $(b, c) \in \mathcal{E}^{ra}$, the values of F_{ba}^r and F_{ca}^{r+1} as successive superscripts.

6	$(6,3)^{11}$	$(3,2)^{11}$ $(3,4)^{11}$	$(2,1)^{11}$ $(2,3)^{11}$ $(4,3)^{11}$ $(4,5)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$ $(3,4)^{11}$ $(3,6)^{11}$ $(5,4)^{11}$	$(2,3)^{12}$ $(4,3)^{12}$ $(6,3)^{12}$	$(3,2)^{21}$ $(3,4)^{21}$ $(3,6)^{21}$	$(2,1)^{11}$ $(2,3)^{11}$ $(4,3)^{11}$ $(4,5)^{11}$ $(6,3)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$ $(3,4)^{11}$ $(5,4)^{11}$	$(2,3)^{11}$ $(4,3)^{11}$	$(3,6)^{11}$
5	$(5,4)^{11}$	$(4,3)^{11}$	$(3,2)^{11}$ $(3,6)^{11}$	$(2,1)^{11}$ $(2,3)^{11}$ $(6,3)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$ $(3,4)^{11}$	$(2,3)^{11}$ $(4,3)^{11}$ $(4,5)^{11}$	$(3,4)^{11}$ $(3,6)^{11}$ $(5,4)^{11}$	$(4,3)^{11}$ $(6,3)^{11}$	$(3,2)^{11}$	$(2,1)^{11}$
4	$(4,3)^{11}$ $(4,5)^{11}$	$(3,2)^{11}$ $(3,4)^{11}$ $(3,6)^{11}$ $(5,4)^{11}$	$(2,1)^{11}$ $(2,3)^{12}$ $(4,3)^{12}$ $(6,3)^{12}$	$(1,2)^{12}$ $(3,2)^{22}$ $(3,4)^{21}$ $(3,6)^{21}$	$(2,1)^{21}$ $(2,3)^{22}$ $(4,3)^{12}$ $(4,5)^{11}$ $(6,3)^{12}$	$(1,2)^{11}$ $(3,2)^{21}$ $(3,4)^{22}$ $(3,6)^{21}$ $(5,4)^{12}$	$(2,3)^{12}$ $(4,3)^{22}$ $(4,5)^{21}$ $(6,3)^{12}$	$(3,2)^{21}$ $(3,4)^{21}$ $(3,6)^{21}$ $(5,4)^{11}$	$(2,1)^{11}$ $(2,3)^{11}$ $(4,3)^{11}$ $(6,3)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$
3	$(3,2)^{11}$ $(3,4)^{11}$ $(3,6)^{11}$	$(2,1)^{11}$ $(2,3)^{12}$ $(4,3)^{12}$ $(4,5)^{11}$ $(6,3)^{12}$	$(1,2)^{12}$ $(3,2)^{22}$ $(3,4)^{22}$ $(3,6)^{21}$ $(5,4)^{12}$	$(2,1)^{21}$ $(2,3)^{23}$ $(4,3)^{23}$ $(4,5)^{21}$ $(6,3)^{13}$	$(1,2)^{12}$ $(3,2)^{32}$ $(3,4)^{32}$ $(3,6)^{32}$ $(5,4)^{12}$	$(2,1)^{21}$ $(2,3)^{23}$ $(4,3)^{23}$ $(4,5)^{21}$ $(6,3)^{23}$	$(1,2)^{12}$ $(3,2)^{32}$ $(3,4)^{32}$ $(3,6)^{31}$ $(5,4)^{12}$	$(2,1)^{21}$ $(2,3)^{22}$ $(4,3)^{22}$ $(4,5)^{21}$ $(6,3)^{12}$	$(1,2)^{11}$ $(3,2)^{21}$ $(3,4)^{21}$ $(3,6)^{21}$ $(5,4)^{11}$	$(2,3)^{11}$ $(4,3)^{11}$ $(6,3)^{11}$
2	$(2,1)^{11}$ $(2,3)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$ $(3,4)^{11}$ $(3,6)^{11}$	$(2,3)^{12}$ $(4,3)^{12}$ $(4,5)^{11}$ $(6,3)^{12}$	$(3,2)^{21}$ $(3,4)^{22}$ $(3,6)^{21}$ $(5,4)^{12}$	$(2,1)^{11}$ $(2,3)^{12}$ $(4,3)^{22}$ $(4,5)^{21}$ $(6,3)^{12}$	$(1,2)^{12}$ $(3,2)^{22}$ $(3,4)^{21}$ $(3,6)^{21}$ $(5,4)^{11}$	$(2,1)^{21}$ $(2,3)^{22}$ $(4,3)^{12}$ $(6,3)^{12}$	$(1,2)^{11}$ $(3,2)^{21}$ $(3,4)^{21}$ $(3,6)^{21}$	$(2,3)^{11}$ $(4,3)^{11}$ $(4,5)^{11}$ $(6,3)^{11}$	$(3,4)^{11}$ $(5,4)^{11}$
1	$(1,2)^{11}$	$(2,3)^{11}$	$(3,4)^{11}$ $(3,6)^{11}$	$(4,3)^{11}$ $(4,5)^{11}$ $(6,3)^{11}$	$(3,2)^{11}$ $(3,4)^{11}$ $(5,4)^{11}$	$(2,1)^{11}$ $(2,3)^{11}$ $(4,3)^{11}$	$(1,2)^{11}$ $(3,2)^{11}$ $(3,6)^{11}$	$(2,3)^{11}$ $(6,3)^{11}$	$(3,4)^{11}$	$(4,5)^{11}$
$\frac{a}{r}$	1	2	3	4	5	6	7	8	9	10

Table 4: E_6 boundary edges

From this table, the properties (4.28) and (4.33) are immediately apparent, and we can also gain some understanding of the nature of each of the 30 boundary conditions at the conformal point.

4.5 Realization of Conformal Boundary Conditions

We now consider the relationship between the integrable boundary conditions of the critical unitary A – D – E lattice models and the conformal boundary conditions of the critical series of $\hat{s}\ell(2)$ unitary minimal conformal field theories.

Each conformal field theory of this type on a torus or cylinder is associated with two graphs, the A graph A_{g-2} and an A , D or E graph \mathcal{G} with Coxeter number g , this theory being denoted $\mathcal{M}(A_{g-2}, \mathcal{G})$. As shown in [16, 17, 18], the lattice model based on \mathcal{G} , with ψ the Perron-Frobenius eigenvector and $0 < u < \lambda$, can be associated with the field theory $\mathcal{M}(A_{g-2}, \mathcal{G})$.

In [9], it was found that the complete set of conformal boundary conditions of $\mathcal{M}(A_{g-2}, \mathcal{G})$ on a cylinder is labeled by the set of pairs (r, a) , with $r \in \{1, \dots, g-2\}$, $a \in \mathcal{G}$ and (r, a) and $(g-r-1, \bar{a})$ being considered as equivalent. We immediately see that this classification is identical to that of the boundary conditions of the corresponding lattice model at the conformal point.

It was also shown in [9] that the partition function of $\mathcal{M}(A_{g-2}, \mathcal{G})$ on a cylinder with conformal boundary conditions (r_1, a_1) and (r_2, a_2) is given by

$$Z_{r_1 a_1 | r_2 a_2}(q) = \sum_{r=1}^{g-2} \sum_{s=1}^{g-1} F(A_{g-2})_{r_1 r_2}^r F(\mathcal{G})_{a_1 a_2}^s \chi_{(r,s)}(q), \quad (4.65)$$

where q is the modular parameter, $F(A_{g-2})^r$ and $F(\mathcal{G})^s$ denote the fused adjacency matrices of A_{g-2} and \mathcal{G} , and $\chi_{(r,s)}$ is the character of the irreducible representation with highest weight

$$\Delta_{(r,s)} = \frac{(r g - s (g-1))^2 - 1}{4 g (g-1)} \quad (4.66)$$

of the Virasoro algebra with central charge

$$c = 1 - \frac{6}{g(g-1)}. \quad (4.67)$$

The equivalence of the (r, a) and $(g-r-1, \bar{a})$ conformal boundary conditions is apparent by using (4.18) and the relation $\Delta_{(g-r-1, g-s)} = \Delta_{(r,s)}$ to observe that the partition function (4.65) is unchanged by applying this transformation to either of the boundary condition labels.

We now assert that, in the continuum scaling limit, the (r, a) boundary condition in the lattice model at the conformal and isotropic point provides a realization of the (r, a) conformal boundary condition of the corresponding field theory. In particular, we expect that, as $N \rightarrow \infty$, the eigenvalues of $\mathbf{D}_{r_1 a_1 | r_2 a_2}^N(\lambda/2, \lambda/2, \lambda/2)$ can be arranged in towers, with each tower labeled by a pair (r, s) and the multiplicity of tower (r, s) given by $F(A_{g-2})_{r_1 r_2}^r F(\mathcal{G})_{a_1 a_2}^s$. We further expect that the j 'th largest eigenvalue in this tower has the form

$$\Lambda_{r_1 a_1 | r_2 a_2}^{(r,s)j} = \exp\left[-2N\mathcal{F} - 2f_{r_1|r_2} + 2\pi(c/24 - \Delta_{(r,s)} - k_{(r,s)j})/N + o(1/N)\right], \quad (4.68)$$

where \mathcal{F} is the bulk free energy per lattice face, which depends only on g , $f_{r_1|r_2}$ is the boundary free energy per lattice row, which depends only on g , r_1 and r_2 , c and $\Delta_{(r,s)}$ are as given in (4.66) and (4.67), and $k_{(r,s)j}$ are nonnegative integers given through the expansion of the Virasoro characters by

$$\chi_{(r,s)}(q) = q^{-c/24 + \Delta_{(r,s)}} \sum_{j=1}^{\infty} q^{k_{(r,s)j}}, \quad k_{(r,s)j} \leq k_{(r,s)j+1}. \quad (4.69)$$

With the eigenvalues appearing in this tower structure, it follows using (3.56) that, as $N \rightarrow \infty$, the lattice model and conformal partition functions are related by

$$\mathbf{Z}_{r_1 a_1 | r_2 a_2}^{NM}(\lambda/2, \lambda/2, \lambda/2) \sim \exp(-2MN\mathcal{F} - 2Mf_{r_1|r_2}) Z_{r_1 a_1 | r_2 a_2}(q), \quad q = \exp(-2\pi M/N). \quad (4.70)$$

We note that we also expect related conformal behavior in a lattice model which is at the conformal point and has $0 < u < \lambda$, but which is no longer at the isotropic point $u = \lambda/2$.

The expectation that the lattice model boundary conditions correspond in this way to the conformal boundary conditions is supported by the results of numerical studies we have performed, the matching of the identifications made here of the nature of the lattice realizations of certain conformal boundary conditions with those made in other studies, the consistency of all of the symmetry properties of the lattice model partition function with those of the conformal partition function, and analytic confirmation in several cases.

In our numerical studies, we evaluated the eigenvalues of $\mathbf{D}_{r_1|_r_2s}^N(\lambda/2, \lambda/2, \lambda/2)$ for certain A graphs, selected values of r_1 , r_2 and s , and several successive values of N . We then extrapolated these results to large N and verified consistency with (4.68) for these cases. This numerical data, used with (4.46), also implied consistency with (4.68) for all of the related A , D and E cases.

Regarding the identification of the nature of the lattice realizations of particular conformal boundary conditions, this was done for all A_3 cases and all D_4 cases except $(2, 0)$ in [1, 19], for all $(1, a)$ and $(r, 1)$ cases of A_{g-1} and $D_{\frac{g}{2}+1}$ in [20], for all A_4 cases in [25], and for the $(2, 0)$ case of D_4 in [29]. In all of these studies, the lattice model boundary conditions were shown to have exactly the same basic features as those found here.

Proceeding to the consistency of symmetry properties, it follows straightforwardly from (4.65) and the properties of the fused adjacency matrices that the $\mathcal{M}(A_{g-2}, \mathcal{G})$ partition function satisfies

$$\begin{aligned}
Z_{r_1 a_1 | r_2 a_2}(q) &= Z_{r_2 a_2 | r_1 a_1}(q) = Z_{r_2 a_1 | r_1 a_2}(q) \\
&= Z_{r_1 \bar{a}_1 | r_2 \bar{a}_2}(q) = Z_{g-r_1-1, \bar{a}_1 | g-r_2-1, \bar{a}_2}(q) \\
\sum_{a_1', a_2' \in \mathcal{G}} F(\mathcal{G})_{a_1 a_1'}^{r_1} F(\mathcal{G})_{a_2 a_2'}^{r_2} Z_{r_1' a_1' | r_2' a_2'}(q) &= \\
\sum_{a_1', a_2' \in \mathcal{G}} F(\mathcal{G})_{a_1 a_1'}^{r_2} F(\mathcal{G})_{a_2 a_2'}^{r_1} Z_{r_1' a_1' | r_2' a_2'}(q) & \\
\sum_{a \in \mathcal{G}} F(\mathcal{G})_{a_1 a}^{s'} Z_{r_1 a | r_2 a_2}(q) &= \sum_{s=1}^{g-1} F(\mathcal{G})_{a_1 a_2}^s Z_{r_1 s' | r_2 s}(q).
\end{aligned} \tag{4.71}$$

We immediately see that these equalities are consistent with the lattice relations (3.65), (3.67), (4.31), (4.40), (3.71) and (4.43) respectively. We also note that certain cases of the last equality of (4.71) and its lattice version (4.43), mostly with $s' = r_1 = r_2 = 1$, were considered numerically and analytically in [1, 20, 21, 22, 23, 24], while in [28] free combinations of $(1, a)$ lattice boundary conditions in A_{g-1} were studied analytically leading to (4.47) with $r_1 = r_2 = 1$ and a sum on a_1 and a_2 . However, in all of these studies, the orientation of the lattice differed from that used here by a rotation of 45 degrees.

Finally, the partition function relation (4.70) has been proved analytically using

techniques based on the Yang-Baxter and boundary Yang-Baxter equations for a lattice with the same orientation as that used here for all A_3 cases in [26] and for all A_4 cases which lead to a single character on the right side of (4.65) in [27].

5. Discussion

We have obtained various results on integrable boundary conditions for general graph-based and, in particular, critical unitary A - D - E lattice models. More specifically, we have systematically constructed boundary weights, derived general symmetry properties and, for the A - D - E cases, studied the relationship with conformal boundary conditions.

The general formalism presented here, or certain natural extensions of it, can be applied to various other integrable lattice models which are associated with rational conformal field theories of interest. We expect that the corresponding integrable boundary conditions provide realizations of the conformal boundary conditions of these theories, although we acknowledge that for many of these models only the bulk weights are currently known and that explicitly obtaining boundary weights may involve certain technical challenges. Nevertheless, in conclusion, we list these other cases and indicate their connections with those studied here:

- If, using (4.7), we choose an eigenvector of an A - D - E adjacency matrix corresponding to a Coxeter exponent k with $1 < k < g-1$ and k coprime to g , then a nonunitary A - D - E model is obtained which corresponds to the nonunitary minimal theory $\mathcal{M}(A_{g-k-1}, \mathcal{G})$. This enables the consideration of all of the $\mathcal{M}(A_{h-1}, \mathcal{G})$ minimal theories with $h < g$. The $\mathcal{M}(A_{h-1}, \mathcal{G})$ theories with $h > g$ and \mathcal{G} a D or E graph can not be obtained in this way, but all of the $\mathcal{M}(A_{h-1}, A_{g-1})$ theories are accessible since in this case h and g are interchangeable.
- By taking, in Section 3, \mathcal{G} as an $A^{(1)}$, $D^{(1)}$ or $E^{(1)}$ Dynkin diagram, and ψ as the Perron-Frobenius eigenvector of its adjacency matrix, lattice models are obtained which correspond to certain conformal field theories with central charge $c = 1$. As noted in Section 3.4.1, for these models s is given by the second case of (2.2) and there are infinitely many fusion levels.

- By replacing the relations of (2.1) with those of the Hecke algebra, certain lattice models and conformal field theories associated with $\hat{sl}(n)$, for $n > 2$, can be obtained. In this case, although the lattice models become significantly different, we expect that most of the results of at least Section 2 remain unchanged
- By using the dilute Temperley-Lieb algebra instead of the Temperley-Lieb algebra, lattice models which correspond to the so-called tricritical series of unitary minimal theories, $\mathcal{M}(A_g, \mathcal{G})$, can be obtained. However, we note that the dilute Temperley-Lieb algebra contains considerably more generators than the Temperley-Lieb algebra, so that the formalism would be more complicated from the outset.
- It is also apparent that lattice models whose bulk weights are given by fused square blocks of A - D - E bulk weights could be considered by applying some relatively straightforward extensions to the formalism. The field theories associated with these models include certain superconformal theories. The cases of the A models involving only diagonal boundary weights were studied in [33], where it was shown that the double-row transfer matrices of the standard and fused model together satisfy a hierarchy of functional equations. We expect that equations of a similar form can be derived, using the boundary inversion relation (3.40) and other local properties, for the remaining A - D - E cases, such equations being important in the analytic determination of transfer matrix eigenvalues.
- Finally, we mention the off-critical A and D models, which can be associated with perturbed conformal field theories. The bulk weights in these cases can no longer be expressed in terms of the Temperley-Lieb algebra, but a fusion procedure still exists and boundary weights constructed from fused blocks of bulk weights attached to diagonal boundary weights still satisfy the boundary Yang-Baxter equation. Some integrable boundary weights are known for these cases, as listed in [34], and it is expected that each of the A and D boundary conditions found here corresponds to a critical limit of an off-critical integrable boundary condition.

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